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System and component modelling and optimisation for an efficient 10kWe low temperature organic Rankine cycle utilising a radial inflow expander

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System and component modelling and optimisation for an efficient 10kW_e low temperature organic Rankine cycle utilising a radial inflow expander

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Abstract

Small scale (10kWe) organic Rankine cycles for low temperature applications such as heat recovery and solar power present a significant development opportunity but limited prototypes have been developed. This paper aims to address this by describing a system modelling tool which is used to select a working fluid, optimise cycle conditions, and preliminarily size a radial inflow rotor for an experimental test rig. The program is a steady-state sizing and optimisation tool which advances on current models by combining component models and cycle analysis with multi-objective optimisation and turbomachinery design aspects. Sizing and off-design pump and expander models are based on non-dimensional characteristic plots, whilst an additional design program achieves an expander rotor design. A novel objective function couples component and system performance with complexity. Results from an optimisation study indicate that R1234ze is the optimal working fluid for the defined objective function with a predicted net power output of 7.32kWe, correlating to a cycle efficiency of 7.26%, and evaporator and condenser areas of 1.59m² and 2.40m² respectively. However, after considering operating pressures and fluid availability, R245fa has been highlighted as the most suitable fluid for a planned experimental radial expander test rig and a preliminary turbine design is proposed.

Keywords

organic Rankine cycles, ORC, radial turbine, small scale expander

Introduction

Over recent years there has been a significant interest in organic Rankine cycles (ORC) to convert thermal energy into power. The ORC differs from the Rankine cycle by using an organic fluid instead of water allowing the conversion of low temperature heat sources such as solar, geothermal and waste heat into power. Within the cycle the expander is the most critical component, and it is important that it operates efficiently considering the low Carnot efficiency of the ORC. Either axial or radial turbo-expanders, or positive-displacement devices such as screw or scroll machines can be employed.

ORMAT, Tri-O-Gen and Turboden have commercialised large scale ORCs employing turbo-expanders,¹⁻³ whilst BEP and Electratherm produce units between 20 and 50kWe utilising screw expanders.^{4,5} With the exception of ENEFTECH, the implementation of scroll expanders remains within experimental systems.⁶ Although bespoke systems are available, the technical challenges such as the development of an efficient expander, reduce the commercial viability of small-scale systems. However, with careful component selection and design, an efficient and economical system could have widespread applications.

Figure 1 presents current small-scale expander research within the literature. There is limited interest in screw expanders for powers below 20kWe due to high leakage flows caused by machining tolerances.^{7, 8,9} Scroll expanders are low cost, have low rotational speeds, and are common within 1 to 3kWe experimental systems.¹⁰⁻¹² However, they remain untested at higher powers, whilst efficiency is limited because the machine is not designed for expansion duties, with values between 60% and 70% reported within the literature.

[Insert Figure 1. Literature review of current small scale low temperature experimental ORC expanders.]

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Radial turbo-expanders are compact, lightweight and show a high level of technical maturity. Furthermore, the low enthalpy drop of organic fluids compared to air allowing high pressure ratios to be efficiently achieved over a single stage. Nguyen et al. and Yamamoto et al. developed experimental ORCs with radial expanders, achieving 1.47kWe and 0.15kWe with expander efficiencies of 49.8% and 48.0% respectively.^{13,14} Pei et al. obtained a 1.1kWe power output with an expander isentropic efficiency of 62.5% and further work increased this to 68%.^{15,16} Kang constructed an experimental rig based on a radial expander, achieving an isentropic efficiency of 78.7% with a 32.7kWe output.¹⁷ Inoue et al. developed and tested an ORC turbo-expander. Results indicate a work output of 13.2kWe with an isentropic efficiency of 80%.¹⁸

Referring to Figure 1, efficient expanders within the 10kWe range are found to be sparse. With the suitability of scroll expanders yet to be proven, and high leakage flows within screw expanders, a well-designed radial expander is the most suitable choice for the objective power. Despite literature suggesting performance deteriorates below 50kWe,^{9,19} an organic fluid actually facilitates a larger rotor diameter than an equivalent 10kWe expander working with air, potentially reducing rotor losses. At optimal design conditions, a well-designed radial expander could achieve an efficiency of 80%, significantly improving on current scroll and screw expanders. Concerns over higher rotational speeds that require high-speed generators and bearings need to be addressed, although the expected rotational speeds remain significantly lower than those within current turbocharger technology.

Computational modelling plays a large part in ORC research and a number of parametric thermodynamic and working fluid studies have been undertaken.²⁰⁻²³ Whilst these studies are valuable, it is necessary to include models to predict component behaviour. Furthermore, due to the large number of interdependencies between cycle parameters an optimisation procedure is essential.²⁴⁻²⁶ However, without economic modelling a major complexity is the definition of suitable objective

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9 functions.²⁷ The definition of an objective function, and the choice of component models will also
10 depend upon whether the model is used for system sizing, or cycle optimisation with a known set of
11 components.
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14 Few researchers have coupled cycle analysis and turbomachinery. Experimental studies make
15 little reference to expander design, whilst cycle analysis typically assumes constant expander
16 efficiencies. A complete model should consider expander design and off-design performance within
17 cycle analysis. Fiaschi et al. developed a 1D design tool, utilising real-fluid properties,¹⁹ whilst Lang et al.
18 considers expander design for high temperature ORCs following the design process outlined by
19 Whitfield & Baines.^{28,29}
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26 Despite the large amount of literature, computational modelling remains the bedrock for ORC
27 research. However, experimental work remains pivotal to validate models and to understand the
28 practical issues involved. This project aims to develop a 10kWe radial inflow expander for low
29 temperature ORCs. This paper outlines the development of a modelling method that combines
30 thermodynamics, component models and multi-objective optimisation. Optimisation and preliminary
31 turbomachinery design leads to the selection of a suitable working fluid and rotor design for an
32 experimental test rig.
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42 **System Modelling**

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44 The simulation program is a 1D model, developed in FORTRAN, and includes REFPROP for real fluid
45 properties. With a defined heat source and sink, the program can either size the system or optimise
46 cycle conditions for a known set of components.
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50 Combining cycle analysis with individual component models allows component behaviour to be
51 considered within the context of cycle analysis. This modular approach advances on current models
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9 within the literature that only consider cycle thermodynamics, whilst allowing alternative component
10 models to be selected for sizing or optimisation. Furthermore alternative models, for example
11 alternative heat exchanger geometries, can be implemented without too much disruption.
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14 The main variables are the condensation temperature T_c , pressure ratio PR , degree of
15 superheat ΔT_{SH} , and evaporator pinch point PP_E . The pinch point is the minimum temperature difference
16 within the evaporator, and is a trade-off between performance and cost. For system sizing the heat
17 exchanger geometry is also variable.
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21 The ORC is assumed to be a steady state, subcritical cycle. Although supercritical cycles enable
22 better matching to the heat source, higher pressures increase system complexity and present more of a
23 safety concern.²⁰ The working fluid is assumed to be a saturated liquid at pump inlet, although a degree
24 of sub-cooling will be required to prevent cavitation. This assumption is valid since the impact of a small
25 sub-cooling on the overall cycle will be small. The working fluid is assumed to be a saturated or
26 superheated vapour at expander inlet as two-phase conditions should be avoided for turbo-expanders.
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28 It is also assumed that no phase change of the heat source or sink occurs as this can significantly impact
29 the design of the heat exchangers.
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33 Within the cycle analysis, heat losses and pressure drops within the system are also neglected.
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35 However, the pressure drops within evaporator and condenser are estimated to ensure the pressure
36 drops within these components remain within allowable limits. For the same expander pressure ratio,
37 system pressure losses will increase the required pump work, although the impact of this is expected to
38 be small.
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42 For a set of input variables, the fluid properties of the heat source, heat sink and working fluid
43 at various points within the cycle are calculated. Each component is then simulated sequentially.
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Pump Modelling

The pump increases the working fluid pressure from the condensation pressure P_1 , to the expander inlet pressure P_2 , specified by the pressure ratio. Defining the pump efficiency as the ratio of ideal to real pump work, the enthalpy h_2 at pump exit can be found if the pump efficiency η_p is known (Equation 1). The enthalpy after an isentropic compression h_{2s} is found as a function of P_2 and the entropy at pump inlet s_1 , since entropy remains constant for an isentropic process ($s_{2s} = s_1$). The pump work per unit mass is the change in enthalpy.

$$h_2 = h_1 + \frac{h_{2s} - h_1}{\eta_p} \quad (1)$$

The simulation model contains pump models for both sizing and cycle optimisation. The sizing model assumes a fixed efficiency. Although this assumption is generally acceptable as pump work remains small compared to expander work, recent work has shown pump work to be more influential within ORCs than conventional Rankine cycles.^{30, 31} For cycle optimisation a method developed by Van Putten et al. creates off-design characteristic curves using known operational points for a specified pump.³² At any operating point, the performance can be described by the non-dimensional head H_{nd} and non-dimensional volume flow rate \dot{V}_{nd} . The relationship between these two parameters can be expressed as a quadratic equation (Equation 4).

$$H_{nd} = \frac{gH}{n_p^2 D_p^2} \quad (2)$$

$$\dot{V}_{nd} = \frac{\dot{V}}{n_p D_p^3} \quad (3)$$

$$H_{nd} = a\dot{V}_{nd}^2 + b\dot{V}_{nd} + c \quad (4)$$

Where n_p and D_p are the rotational speed and diameter of the pump respectively, g is the acceleration due to gravity, \dot{V} is the volumetric flow rate, and H is the head (Equation 5); ρ_1 and ρ_2 refer to the fluid density at the inlet and outlet of the pump respectively.

$$H = \frac{P_2 - P_1}{\frac{1}{2}(\rho_1 + \rho_2)g} \quad (5)$$

The pump performance at the design point, and the operating points at which the head and volumetric flow rates are equal to zero, then provide the quadratic coefficients. For a given pressure ratio and working fluid flow rate, the pump efficiency η_p is obtained by Equation 6.²⁰ The subscript “d” refers to the design point.

$$\eta_p = \eta_d \left[1 - \left(1 - \frac{\dot{V} n_p}{\dot{V}_d n_d} \right)^2 \right] \quad (6)$$

Evaporator Modelling

The evaporation process is divided into three stages; single-phase preheating, two-phase evaporation and single-phase superheating. The working fluid mass flow rate is calculated using the desired expander inlet conditions, the input heat source, and the evaporator pinch point. The heat exchanger is then sized to meet this specification. Although the current model assumes a double pipe counter flow arrangement, a more realistic shell and tube model is currently in development.

Applying the first law of the thermodynamics, and referring to Figure 2, the evaporator energy balances are expressed by Equations 7, 8 and 9. These equations express the product of the working fluid mass flow rate \dot{m}_{orc} and a change in working fluid enthalpy h , to the product of the heat source mass flow rate \dot{m}_{wh} and a change in the heat source enthalpy h_{wh} . Solving these equations obtains the working fluid mass flow rate and the heat source temperatures at evaporator exit and the point at which the working fluid is a saturated vapour.

$$\dot{m}_{orc}(h_{2'} - h_2) = \dot{m}_{wh}(h_{wh,pp} - h_{wh,o}) \quad (7)$$

$$\dot{m}_{orc}(h_{3'} - h_{2'}) = \dot{m}_{wh}(h_{wh,ei} - h_{wh,pp}) \quad (8)$$

$$\dot{m}_{orc}(h_3 - h_{3'}) = \dot{m}_{wh}(h_{wh} - h_{wh,ei}) \quad (9)$$

[Insert Figure 2. Schematic of the temperature distribution and heat transfer process between the heat source (top line) and the working fluid (bottom line) in a typical ORC evaporator.]

To account for variations in fluid properties, each heat transfer stage is discretised into a number of elements over which a constant change in working fluid enthalpy is assumed. The enthalpy of

the working fluid at each stage is known and therefore the change in enthalpy within each discrete element is the total change in enthalpy divided by the number of elements. Starting at a point where the conditions of both fluids are known, for example at the evaporator exit (h_3, h_{wh}) or at the pinch point ($h_2', h_{wh,pp}$), an energy balance obtains the temperature of the heat source. After calculating the Log-Mean-Temperature-Difference within each element and relating the energy balance to a heat transfer process (Equation 10), the required heat transfer area A_i is obtained if the overall heat transfer coefficient U_i is known.

$$\dot{m}_{orc}(h_{out,i} - h_{in,i}) = U_i A_i LMTD_i \quad (10)$$

The total evaporator area is the summation of each discrete element within each heat transfer stage.

$$A_E = \sum_{i=1}^n A_{ph,i} + \sum_{i=1}^n A_{ev,i} \sum_{i=1}^n A_{sh,i} \quad (11)$$

U_i is calculated by breaking the heat transfer process into three thermal resistances consisting of two convection terms either side of the wall, and a conduction term through the wall. U_i is therefore a function of geometry, thermal conductivity of the wall and the local convective heat transfer coefficients. For the calculation of the local heat transfer coefficients, Gnielinski's correlation for turbulent flow within tubes is applied for all single-phase flows.³³ Chen's correlation for two-phase

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9 evaporation remains one of the most successful correlations for saturated boiling and is applied to the
10 working fluid.³³

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12 Despite ignoring pressure drops within the cycle analysis, a design check is required to restrict
13 sizing optimisations from converging to very small pipe diameters which would experience large
14 pressure drops, significantly increasing working fluid and auxiliary pumping work. For single-phase flow
15 through a pipe of length L , the pressure drop ΔP_L is given by Equation 12; f is the friction factor, D_h is the
16 hydraulic diameter, ρ_{av} is the average density, and u is the flow velocity.
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$$\Delta P_L = f \left(\frac{L}{D_h} \right) \left(\frac{\rho_{av} u^2}{2} \right) \quad (12)$$

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30 For two-phase flow, the Müller-Steinhagen and Heck correlation has been proven to provide
31 suitably accurate results and has been deployed within the simulation program.³⁴
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38 *Expander Modelling*

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40 Expressing the expander isentropic efficiency as the ratio of real to ideal work, the expander outlet
41 conditions are determined if the expander efficiency η_e , expander inlet conditions, and outlet pressure
42 P_4 are known (Equation 13). The work output per unit mass is the change in enthalpy. The isentropic
43 enthalpy at expander outlet h_{4s} is found based on P_4 and assuming an isentropic expansion ($s_{4s} = s_3$).
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$$h_4 = h_3 - \eta_e (h_3 - h_{4s}) \quad (13)$$

Expander Sizing. For the application and power range considered a radial turbine has been highlighted as the most suitable expander. At optimal conditions a radial turbine can achieve efficiencies in excess of 85%, although as the design mass flow rate reduces, the isentropic efficiency will reduce as the size of clearance gaps relative to the rotor size increases. However, a target efficiency of 80% is achievable, surpassing the current efficiencies of screw and scroll expanders within this power range. For this specified efficiency, and defined thermodynamic conditions the non-dimensional specific-speed N_s and specific-diameter D_s may be used to determine the rotational speed ω and rotor diameter D_e respectively. \dot{V}_4 is the volumetric flow rate at the expander outlet and $(h_3 - h_{4s})$ is the isentropic enthalpy drop across the expander.

$$N_s = \frac{\omega \dot{V}_4^{\frac{1}{2}}}{(h_3 - h_{4s})^{\frac{3}{4}}} \quad (14)$$

$$D_s = \frac{D_e (h_3 - h_{4s})^{\frac{1}{4}}}{\dot{V}_4^{\frac{1}{2}}} \quad (15)$$

The efficiency of radial inflow expanders have been correlated against N_s and D_s by Watson & Janota.³⁵ Figure 3 shows that optimal efficiencies above 80% are achieved with N_s ranging between 0.4 and 0.8 and D_s ranging between 3 and 5. The centre point correlates to $N_s = 0.6$ and $D_s = 3.4$. Therefore using these values the required diameter and rotational speed for a given mass flow rate, inlet conditions, can be obtained by rearranging Equations 14 and 15.

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Using N_s and D_s in this way to size the rotor allows a quick design check to see whether the required expander is within practical limits, whilst enabling expander design aspects to be considered within a parametric working fluid selection study. It is important to note these are only characteristic results and a complete design will require a more detailed analysis. Following a parametric study, a working fluid with optimal cycle conditions will be obtained, and a 1D through-flow model will result in a more detailed rotor design. A simple method based on standard radial turbine design theory is outlined later.

[Insert Figure 3. Digitisation of obtainable efficiency contours for radial inflow turbines correlated against specific speed and specific diameter by Watson & Janota.³⁵]

Expander Off-Design Performance. During cycle analysis with an existing expander, it is not suitable to assume that the expander performance remains at the design point. A performance map must be **implemented** to estimate the expander performance at a particular operating point. In coupling a thermodynamic cycle analysis with an expander performance map the optimal system may not necessarily operate at the expander's design point. In **order** words, expander efficiency **may be sacrificed for more preferential cycle conditions.**

Operating at off-design pressure ratios and rotational speeds reduces the isentropic efficiency of the expander. The main source of this loss is attributed to an incidence loss, **causing flow separation and recirculation within the rotor passage.** Passage, windage and clearance losses must also be considered, although these effects will vary less significantly **with** off-design conditions. Although 1D performance models are available for radial turbines these are empirically **based using experimental data from air turbines.** **The validity of these models for organic fluids is unproven,**

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requiring either CFD or experimentation to obtain performance maps. **Currently** a more generic formulation of expander performance **is** considered just to highlight the intended methodology, which will be replaced in future studies.

Figure 3 **has been** digitised into a Look-Up Table, which can be accessed within the simulation program. For given expander conditions and rotational speed an estimate of efficiency can be obtained. Although this is useful as a generic characteristic, caution should be taken as the N_s and D_s values used to obtain Figure 3 refer only to the design point efficiency. **N_s is considered a shape factor with low values indicating a large diameter with small blade heights and therefore small passage areas. Comparatively, a higher value indicates a smaller rotor diameter with a larger flow passage resulting in a higher exit velocity. For the same turbine rotor it is impossible for the rotor geometry to change.**

Condenser Modelling

The condenser is divided into two heat transfer regions: single-phase precooling and two-phase condensation. Applying the first law of thermodynamics, with reference to Figure 4, the energy balances are expressed by Equations 16 and 17. These equations express the product of the working fluid mass flow rate and a change in enthalpy, to the product of the heat sink flow rate \dot{m}_c and a change in heat sink enthalpy h_c . For a fixed \dot{m}_c solving these equations leads to the condenser pinch point and the heat sink outlet temperature.

$$\dot{m}_{orc}(h_4 - h_{4'}) = \dot{m}_c(h_{c,o} - h_{c,pp}) \quad (16)$$

$$\dot{m}_{orc}(h_{4'} - h_1) = \dot{m}_c(h_{c,pp} - h_c) \quad (17)$$

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11 [Insert Figure 4. Schematic of the temperature distribution and heat transfer process between the heat
12 sink (bottom line) and the working fluid (top line) in a typical ORC condenser.]
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16 The condenser is modelled with a double pipe counter flow arrangement, and is sized to ensure
17 that the heat sink and working fluid conditions are met. The same discretisation process, and pressure
18 drop calculation, outlined for the evaporator is applied. Gnielinski's correlation is used for single-phase
19 heat transfer whilst Shah's correlation is applied for two-phase condensation.³³
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25 26 **Turbomachinery Design Aspects**

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28 The results from the cycle analysis will  gain the thermodynamic conditions, the rotor diameter and
29 rotor rotational speed for a given working fluid. However, in order to develop an experimental
30 prototype a 1D through-flow model is required to obtain a more detailed rotor design. Radial
31 expander rotor design is well covered within textbooks²⁰ so only the key aspects of the model will be
32 outlined here. REFPROP has again been utilised for fluid properties instead of the standard ideal gas
33 laws.¹⁹
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40 The rotor design is based on a number of non-dimensional parameters which are set
41 according to values suggested within the literature. To arrive at a preliminary design these parameters
42 are currently fixed, although future work will optimise these parameters to arrive at a more optimal
43 design.
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48 The first two parameters are the isentropic velocity ratio v and the exit velocity ratio ϕ_3 . v is
49 the ratio of blade tip speed U_2 to spouting velocity c_o , where c_o is equivalent to the isentropic enthalpy
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drop across the expander. The exit velocity ratio is the ratio of the axial flow velocity at rotor exit c_{m3} to U_2 . The subscripts 2 and 3 refer to rotor inlet and outlet respectively.

[Insert Figure 5. Radial turbine rotor geometry viewed from the meridional plane (left), and rotor inlet (top right) and rotor outlet (bottom right) velocity triangles. C and W correspond to absolute and relative velocity respectively.]



Rodgers & Geiser correlated expander efficiency against these v and ϕ_3 and found a peak in efficiency at $v = 0.7$ and $\phi_3 = 0.25$.³⁶ For specified thermodynamic conditions c_o and therefore U_2 is easily found. For a specified blade number, the optimal flow angles at the rotor inlet are then obtained by correlations found in Dixon.³⁷

The rotor geometry is shown in Figure 5 and is sized based on the rotor radius ratio ($\epsilon = r_2/r_{3,rms}$), and the exducer radius ratio ($\xi = r_{3h}/r_{3s}$). These are set to 1.67 and 0.45 respectively according to suggestions within Dixon.³⁷ The stator and rotor loss coefficients account for losses within the stator and rotor passages respectively. Following the suggestions made by Dixon and Whitfield & Baines these have been set to 0.11 and 0.66 respectively.^{29,37}

With fixed radius ratios and passage loss coefficients, the rotor outlet velocity triangle is fully defined. ϕ_3 can then be computed using the obtained value of c_{m3} , and the rotor can be sized to pass the required mass flow rate. A parametric investigation of the blade number is undertaken, and the blade number that results in a value of ϕ_3 closest to 0.25 is selected.

Optimisation

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9 For optimisation with respect to an objective function MINUIT has been implemented within the
10 program. MINUIT is a numerical minimisation program that contains a number of minimisation
11 algorithms. The source files are publically available and can be directly coupled to the ORC program.
12
13 The developed optimisation program continues the theme of modularity, allowing either system
14 sizing or cycle optimisation. The optimisation strategy is shown in Figure 6, and the differences such
15 as the number of variables, the component models selected and the defined objective functions are
16 highlighted.
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22 System sizing is considered when designing a system for a particular application. This allows
23 the thermodynamic cycle to be optimised assuming that each component performs at its design point.
24 This simplifies the pump and expander models as a desired component efficiency can be specified.
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26 These components will then be effectively designed to achieve these efficiencies. However, it also
27 introduces more optimisation variables and requires a more complex objective function. Cycle
28 optimisation requires obtaining the best thermodynamic performance with pre-selected components.
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30 This is common within small scale applications where the same set of components may be optimised
31 for different heat sources. Therefore one cannot assume that cycle components are operating at the
32 design point, and off-design performance maps must be included. This is particularly pertinent for the
33 expander where the expander isentropic efficiency will reduce at off-design pressure ratios and
34 rotational speeds.
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44 Within this paper the intention is to size the components for an optimised thermodynamic
45 cycle for a given heat source and sink. Therefore the required optimisation method is for sizing. To
46 demonstrate the cycle analysis optimisation requires a performance map for a suitable ORC radial
47 expander. This is not currently available and therefore a turbine design must first be obtained and
48 tested using either CFD techniques or experimental results. Nonetheless, the cycle optimisation
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9 methodology is included for the sake of completeness and will be fully implemented when an
10 expander performance map is available.
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14 [Insert Figure 6. The optimisation strategy employed within the ORC program for both sizing and cycle
15 optimisation.]
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18 19 20 *Cycle Optimisation* 21

22 For cycle optimisation, the intention is to achieve the greatest performance for a given heat source, heat
23 sink and set of pre-selected components. System performance can be measured by cycle efficiency η_{orc} ,
24 or net power output ($W_e - W_p$). It has been widely shown that these parameters do not share an optimal
25 point because the interaction between the heat source and working fluid is not considered within the
26 cycle efficiency calculation. An optimal cycle efficiency could well result in a poor utilisation of the heat
27 source, whilst a lower cycle efficiency could have a better utilisation of the heat source, therefore
28 producing a higher work output.
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36 For waste heat recovery it is important to achieve the best utilisation of the heat source, and
37 therefore maximise the work output. However, in an application such as cogeneration where the
38 remaining heat is utilised, maximising cycle efficiency might be more appropriate.
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42 In either case, with pre-selected components it is assumed that the investment costs have
43 already been incurred, removing any trade-off between system performance and complexity. This
44 results in an objective function of minimising the inverse of net power or efficiency with respect to the
45 condensation temperature, pressure ratio, degree of superheat and the evaporator pinch point.
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$$\min f(\mathbf{x}) = \frac{1}{W_e - W_p} \quad (18)$$

Or;

$$\min f(\mathbf{x}) = \frac{1}{\eta_{orc}} \quad (19)$$

$$\mathbf{x} = [T_1 \quad PR \quad \Delta T_{sh} \quad PP_e]$$

Sizing Optimisation

For system sizing the objective function must trade-off performance with complexity. Complexity is closely related to cost, and manifests itself through larger heat exchangers and increasing rotor rotational speed. Maximising power output will lead to small pinch points and large heat exchangers. Some researchers consider minimising heat exchanger area per unit power. However, this can lead to systems with small heat exchangers that do not make full utilisation of the available heat source.²⁶ A method to define a more suitable multi-objective function is now described which aims to:

- Maximise net power output, W_n
- Minimise evaporator area, A_E
- Minimise condenser area, A_C
- Minimise rotor rotational speed, N

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	Net work	Expander speed	Evaporator area	Condenser area	$\sum 1's$	Normalised	Importance factor
Net work	X	1	1	1	3	4	0.4
Expander speed	0	X	0	0	0	1	0.1
Evaporator area	0	1	X	1	2	3	0.3
Condenser area	0	1	0	X	1	2	0.2
Total						10	1.0

Table 1. Binary matrix for ranking the sizing optimisation objectives.

These objectives are first ranked using a binary matrix (Table 1). At each element within the matrix the row objective is compared to the column objective. If the row objective is considered more important than the column objective, that element scores 1, otherwise 0. After completion, the numbers of 1's in each row are summed up and normalised by adding one. This normalisation ensures that the lowest ranked objective is still considered even if its tally is zero. The importance factors are obtained by dividing the normalised values by the sum of all the normalised values.

The multi-objective function can then be expressed as the summation of each objective, multiplied by its importance factor a (Equation 20). A reference factor scales each objective to the same order of magnitude. In the absence of scaling, the importance factors become meaningless. It is worth noting that maximising an objective is the same as minimising the reciprocal of that objective.

$$\min f(\mathbf{x}) = a_1 \left(\frac{W_{n,\text{ref}}}{W_n} \right) + a_2 \left(\frac{A_E}{A_{E,\text{ref}}} \right) + a_3 \left(\frac{A_C}{A_{C,\text{ref}}} \right) + a_4 \left(\frac{N}{N_{\text{ref}}} \right) \quad (20)$$

Initial results showed significant variation with different evaporator and condenser reference factors. Low reference values resulted in low output powers suggesting that power is sacrificed for smaller heat exchangers. An improved objective function aims to:

- Maximise net power output, W_n
- Minimise evaporator area per net power output, A_E/W_n
- Minimise condenser area per net power output, A_C/W_n
- Minimise rotor rotational speed, N

The resulting multi-objective function is driven by power output within three of the objectives. Results for this objective function showed much less sensitivity to the reference factors, whilst a comparison of the percentage breakdown of the objective function to the importance factors further confirmed its suitability.

$$\min f(\mathbf{x}) = a_1 \left(\frac{W_{n,\text{ref}}}{W_n} \right) + a_2 \left(\frac{W_{n,\text{ref}}}{W_n} \frac{A_E}{A_{E,\text{ref}}} \right) + a_3 \left(\frac{W_{n,\text{ref}}}{W_n} \frac{A_C}{A_{C,\text{ref}}} \right) + a_4 \left(\frac{N}{N_{\text{ref}}} \right) \quad (21)$$

Despite this confirmation, the chosen objective function is not ideal as objective ranking and scaling requires a qualitative understanding of the problem, thereby relying on designer experience. A more accurate method would quantify system complexity by developing economic models that could

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9 estimate the cost of each component. An objective function of minimising the system cost per unit
10 power could then be used which would remove any reliance on designer knowledge.
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12 13 14 **Results and Working Fluid Selection** 15

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17 Due to the large diversity of ORC applications there is no single optimal working fluid, and fluid
18 screening remains an important stage for any ORC project. A fluid must have preferential thermo-
19 physical properties, be chemically stable within the operating range, environmentally friendly,
20 economically viable, non-corrosive, non-toxic and non-flammable.^{20, 22, 27, 38} Fluids whose vapour dome
21 has an infinite or positive gradient ensure superheated vapour at rotor exit without requiring a
22 superheater. Steeper gradients have the advantage of requiring no recuperation.
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29 A review of screening studies resulted in 50 potential fluids. Considering suitable operating
30 conditions, the evaporation and condensation pressures were calculated. Fluids with sub-atmospheric
31 condensation pressures or supercritical evaporation pressures were neglected. After removing any
32 banned fluids, this list reduced to the 18 fluids (Table 2). Common refrigerant mixtures were neglected
33 as these were found to have high saturation pressures, near critical evaporator pressures or negative
34 gradient saturated vapour domes.
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41 For the remaining fluids, the sizing optimisation was undertaken with the inputs outlined in
42 Table 3 and 4. The optimisation results are presented in Table 5.
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45 Of the 18 fluids considered, 3 did not converge. R134a and R152a have negative gradient
46 vapour domes, which require superheating to ensure a dry expansion. A condensation temperature of
47 313K would also lead to high condensation pressures of 10.1 and 9.1bar respectively. R1234yf also has a
48 high condensation pressure of 10.1bar, which after compression would result in operation close to the
49 critical point.
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Name		Value	Units
Heat source fluid	-	Water	-
Heat source temperature	T_{wh}	390	K
Heat source pressure	P_{wh}	2.0	bar
Heat source flow rate	\dot{m}_{wh}	0.75	kg/s
Heat sink fluid	-	Water	-
Heat sink temperature	T_c	288	K
Heat sink pressure	P_c	1.01	bar
Heat sink flow rate	\dot{m}_c	1.50	kg/s
Pump isentropic efficiency	η_P	70	%
Expander isentropic efficiency	η_E	80	%
Evaporator wall thickness	th_e	1.0	mm
Condenser wall thickness	th_c	2.0	mm

Table 3. Fixed inputs for the ORC sizing optimisation study.

For the converged solutions, the optimal condensation temperature ranges from 311.81K for Isopentane to 316.44K for R227ea. The evaporator and condenser pinch points range from 11.72K for RC318 to 15.35K for Isopentane, and 11.37K for R124 and 13.79K for R236ea respectively. For all fluids the optimisation converges to a solution where the superheat is negligible. This confirms the widespread view that there is no thermodynamic benefit in superheating ORCs.

Name		Starting value	Initial step size	Units
Condensation temperature	T_1	310	10	K
Pressure ratio	PR	3.0	0.25	-
Degree of superheat	ΔT_{sh}	15	5	K
Evaporator pinch point	PP_E	15	5	K
Evaporator inner tube diameter	$D_{i,E}$	60	10	mm
Evaporator outer tube diameter	$D_{o,E}$	100	10	mm
Condenser inner tube diameter	$D_{i,C}$	80	10	mm

Condenser outer tube diameter	$D_{o,c}$	120	10	mm
		Importance factor	Reference value	Units
Net power output	W_n	0.4	22.5	kW_e
Evaporator area	A_E	0.3	2.25	m^2
Condenser area	A_C	0.2	2.25	m^2
Rotor rotational speed	N	0.1	25000	RPM

Table 4. Input variables and initialisation values for the ORC sizing optimisation study.

The expander pressure ratio shows the most variation with optimal values ranging from 2.57 for Isobutane to 3.28 for Isopentane. The relationship between pressure ratio and condensation pressure, pump work and expander work has been investigated in Figure 7. A strong correlation between increasing condensation pressure and increasing pump and expander work is found. The enthalpy change for a constant pressure ratio increases with increasing condensation pressure. Therefore, for the same mass flow rate the required pump work and achievable expander work must increase. Figure 7(c) shows the net effect of increased pump and expander work. It shows that these two effects cancel each other out, with only small variations in net power being obtained over the range of considered working fluids and corresponding condensation temperatures. Figure 7(d) shows the relation between condensation pressure and pressure ratio. Generally, with increasing condensation pressure, the optimal pressure ratio reduces.

[Inset Figure 7. Variation in ORC performance with condensation pressure resulting from the sizing optimisation. (a) expander work (b) pump work (c) net work (d) pressure ratio.]

Overall these results indicate that regardless of the optimal pressure ratio and condensation pressure, the optimisation converges to a solution with a similar net power output for all fluids. Coupled

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9 with the small variations in other thermodynamic variables, it seems the most suitable working fluid is
10 the fluid that results in the most favourable expander and heat exchanger design.

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12 Figure 8, 9 and 10 display the optimisation results with reference to the objective function
13 value, the heat exchanger design and expander design respectively.
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18 [Insert Figure 8. Sizing optimisation results for the 15 working fluids considered. (Bars indicate the
19 objective function value (Equation 21) and the crosses indicate condensation pressure.)
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22 [Insert Figure 9. Evaporator and condenser areas that resulted from the sizing optimisation for the 15
23 working fluids considered.]
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26 [Insert Figure 10. Expander rotational speed and rotor diameter required for the optimised cycles that
27 resulted from the sizing optimisation.]
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32 R1234ze achieves the lowest objective function, followed by R142b and Butane, with values of
33 2.597, 2.692 and 2.737 respectively. From Figure 9 it is apparent that these fluids achieve the smallest
34 heat exchanger areas, therefore suggesting that the optimisation is driven by the minimisation of heat
35 exchanger area. **There is no significant correlation suggesting that these lower heat exchanger areas
36 are the result of slightly higher pinch points. Furthermore, there is no correlation between changes in
37 the working fluid mass flow rate and the resulting heat exchanger area. This suggests minimising the
38 heat exchanger area is largely dependent upon the predicted pressure loss, with a fluid that has a
39 lower predicted pressure drop permitting a smaller pipe diameter to be used. This is an interesting
40 result highlighting that certain fluids may be a more optimal choice when considering heat exchanger
41 design. This analysis should be extended to consider more complex heat exchanger geometries such
42 as a shell-and-tube arrangement.**
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	N (RPM)	D_2 (mm)	b_2 (mm)	D_3 (mm)	D_5 (mm)	D_h (mm)	L (mm)	Ma_2 (-)	Ma_3 (-)
R123	38737	67.04	4.20	40.22	51.87	23.34	21.40	0.91	0.64
R124	60406	40.48	2.58	24.29	31.33	14.10	12.92	0.93	0.61
R141b	45072	66.90	4.20	40.14	51.77	23.29	21.35	0.91	0.64
R142b	71863	39.23	2.63	23.54	30.36	13.66	12.52	0.88	0.59
R227ea	49765	41.30	2.58	24.78	31.96	14.38	13.18	0.97	0.61
R236ea	50322	48.89	3.07	29.33	37.83	17.02	15.60	0.93	0.62
R236fa	52230	45.11	2.86	27.07	34.91	15.71	14.40	0.93	0.61
R245ca	46470	60.55	3.71	36.33	46.85	21.08	19.33	0.93	0.64
R245fa	52230	52.00	3.22	31.20	40.24	18.11	16.60	0.92	0.64
R1234ze	70622	35.45	2.31	21.27	27.43	12.34	11.32	0.92	0.60
BUTANE	95203	39.54	2.68	23.72	30.60	13.77	12.62	0.87	0.59
IBUTAN	100839	36.12	2.45	21.67	27.95	12.58	11.53	0.87	0.58
PENTANE	59050	64.14	4.05	38.48	49.63	22.33	20.47	0.91	0.63
ISOPENTANE	71352	54.95	3.31	32.97	42.52	19.13	17.54	0.94	0.65
RC318	47032	45.82	2.68	27.49	35.45	15.95	14.62	1.01	0.65

Table 6. Resulting expander rotors from the 1D through-flow design program based on the optimised cycle conditions.

Neglecting Isobutane and Butane, expander rotational speeds vary from 40,700rpm for R123 to 75,089rpm for Isopentane, whilst rotor diameter varies from 34.77mm for R1234ze to 65.74mm for R123. Despite R1234ze and R142b having the lowest objective functions, they result in the highest rotational speeds. This indicates that during the optimisation, expander rotational speed is sacrificed for reduced heat exchanger area.

Using the thermodynamic results, the rotor geometry for each  working fluid was obtained using the 1D through-flow expander model (Table 6). Following the assumptions outlined within the turbomachinery design section, the fixed values assumed for ν , ϕ_3 , ϵ and ξ result in a

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9 constant specific speed of 0.58 and specific diameter 3.44 for each ORC rotor. This confirms that this
10 set of design parameters is suitable for obtaining a rotor design that lies within the optimal range
11 shown in Figure 3, with the resulting rotor diameters and rotational speeds agreeing with results from
12 the optimisation study. The turbine designs all comprise of 13 blades, with respective absolute and
13 relative flow angles of 73.7° and -32.6° at rotor inlet, and 9.24° and -64.3° at rotor outlet. The low
14 absolute flow angle at rotor outlet will ensure minimal exit swirl. The degree of reaction is 0.55, which
15 alongside N_s and D_s lies within the optimal ranges suggested within the literature. This suggests that
16 a good turbine efficiency can be expected. The working fluid Mach numbers Ma have been included in
17 Table 6. Due to the low speed of sound of organic fluids, some Mach numbers at rotor inlet are found to
18 be transonic. This could introduce uncertainties within the rotor design, and may also mean a
19 supersonic stator is required.

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30 With the obtained thermodynamic and geometric results from Table 5 and 6 respectively, a
31 more detailed rotor design phase will be completed, followed by CFD analysis. Varying the
32 turbomachinery design inputs that are currently fixed, may result in preferential design, but nonetheless
33 these preliminary designs are expected to offer a good starting point.

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38 Despite the higher rotational speed, the optimisation results for the defined objective function
39 indicate that R1234ze would be the most suitable working fluid for the defined heat source and sink.
40 However, it also has the highest condensation pressure of 8.13bar, resulting in an expander inlet
41 pressure of 21.64bar. This creates more stringent design constraints, which may increase system
42 complexity and cost. Comparatively R142b has the second lowest objective function with condensation
43 and evaporation pressures of 5.38bar and 14.47bar respectively. However R142b is a HCFC and is to be
44 phased out as a result of the Kyoto protocol. The main conclusion from this optimisation study is that
45 the working fluid selection is not as clear-cut as selecting the fluid with the lowest objective function.
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Even with a complex objective function additional factors such as operating pressures, environmental properties or availability impact the decision.

Considering the experimental test rig, the fluid should have a reasonably low condensation pressure to reduce complexity, whilst being readily available. Of the 6 working fluids with a condensation pressure below 3bar, R245fa and Pentane have the lowest objective function values.

Both fluids sit within a group of fluids with similar heat exchanger configurations, with total evaporator and condenser areas of 1.75m^2 and 3.77m^2 for Pentane, and 1.95m^2 and 3.90m^2 for R245fa respectively. The R245fa expander has a lower rotational speed and rotor diameter of 52,230rpm and 52.00mm respectively, compared to 59,050rpm and 64.14mm for Pentane. Based on this R245fa seems the most suitable considering that one objective was the reduction of rotor rotational speed, and that the R245fa rotor has a smaller diameter therefore requiring less material.

R245fa is available within the market, has widely been acknowledged as a suitable low temperature ORC working fluid, and has previously been employed in a number of experimental ORC studies. This study therefore further validates the suitability of R245fa for these applications. More novel working fluids such as the next generation HFOs like R1234ze may prove a more effective solution, and these should be considered within future studies.

Conclusion

Small scale ORCs have yet to reach maturity for commercial application because of the lack of a suitable expander. Whilst there have been continual developments at powers below 5kWe, this study has highlighted a gap within the 10kWe range where there have been limited experimental studies. At this power range, a radial expander is the most suitable choice and a system simulation program has been developed to size components and optimise cycle conditions for a radial expander based ORC.

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9 The results indicated that R1234ze is the optimal working fluid with reference to the novel
10 objective function. However, this study has also highlighted the difficulty in defining a suitable
11 optimisation objective function when economics are not considered. Even after running an optimisation
12 procedure the selection of a suitable working fluid requires a consideration of qualitative factors, and
13 often relies upon the experience and opinions of the ORC designer.
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18 After consideration, R245fa has been selected as a suitable working fluid for an experimental
19 test rig. A preliminary rotor design has been achieved which will be further developed, validated using
20 CFD and constructed into a working experimental prototype before being tested and characterised. The
21 performance map will then be available for further optimisation studies.
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30 funding this research.
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Appendix A

Notation

a	Optimisation importance factor
A	Heat exchanger area, m^2
C_{m3}	Expander axial exit flow velocity, m/s
C_o	Expander spouting velocity, m/s
D	Diameter, m
D_h	Hydraulic diameter, m
D_s	Specific diameter
f	Friction factor
g	Acceleration due to gravity, $kg\ m/s^2$
h	Enthalpy, J/kg
H	Head, m
H_{nd}	Non-dimensional head
L	Heat exchanger pipe length, m
$LMTD$	Log Mean Temperature Difference, K
\dot{m}	Mass flow rate, kg/s
Ma	Mach Number
N	Rotational speed, RPM
n	Rotational speed, RPS
N_s	Specific speed
P	Pressure, bar
PP	Pinch point temperature difference, K
PR	Pressure ratio
r_2	Rotor inlet radius, m
$r_{3,rms}$	Rotor outlet root mean squared radius, m
r_h	Rotor shroud radius, m
r_s	Rotor hub radius, m
s	Entropy, J/kg K
T	Temperature, K
u	Fluid velocity, m/s
U	Overall heat transfer coefficient, $W/m^2\ K$

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9	U_2	Expander blade tip speed, m/s
10	\dot{V}	Volumetric flow rate, m ³ /s
11	\dot{V}_{nd}	Non-dimensional volumetric flow rate
12	W_n	Net work output, W
13	η	Efficiency
14	v	Expander isentropic velocity ratio
15	ρ	Density, kg/m ³
16	ϕ_3	Expander exit flow velocity ratio
17	ω	Rotational speed, rad/s
18	ΔP_L	Heat exchanger pressure drop, Pa
19	ΔT_{sh}	Degree of superheat, K
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Subscripts

23	av	Average
24	C	Condenser
25	c	Heat sink fluid
26	c,o	Heat sink fluid at condenser outlet
27	c,pp	Heat sink fluid at condenser pinch point
28	co	Condensation
29	d	Design point
30	E	Evaporator
31	e	Expander
32	ev	Evaporation
33	orc	Working fluid
34	p	Pump
35	pc	Precool
36	ph	Preheat
37	ref	Reference value
38	sh	Superheat
39	wh	Waste heat source fluid
40	wh,ei	Waste heat source at start of evaporation
41	wh,o	Waste heat source at evaporator outlet
42	wh,pp	Waste heat source at evaporator pinch point
43	1	Pump inlet
44	2	Pump outlet / evaporator inlet
45	2'	Working fluid in evaporator (saturated liquid)
46	2s	Pump outlet after isentropic compression
47	3	Evaporator outlet / expander inlet
48	3'	Working fluid in evaporator (saturated vapour)
49	4	Expander outlet / condenser inlet
50	4'	Working fluid in condenser (saturated vapour)
51	4s	Expander outlet after isentropic expansion
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Working fluid	Series	ALT	ODP	GWP	Toxicity	Flammability	Molecular mass (g/mol)	Critical temperature (K)	Critical pressure (bar)	Saturation pressure @ 313K (bar)	dS/dT for PR=4	Group	
R-123	2,2-dichloro-1,1,1-trifluoroethane	Ethane	1.3	0.02	77	B	1	153.0	456.8	36.6	1.5	0.34	HCFC
R-124	2-chloro-1,1,1,2-tetrafluoroethane	Ethane	5.8	0.022	609	A	1	136.5	395.4	36.2	5.9	0.07	HCFC
R-141b	1,1-dichloro-1-fluoroethane	Ethane	9.3	0.11	725			117.0	477.5	42.1	1.3	0.15	HCFC
R-142b	1-chloro-1,1-difluoroethane	Ethane	17.9	0.065	2310	A	2	100.5	410.3	40.6	5.2	-0.05	HCFC
R-134a	1,1,1,2-tetrafluoroethane	Ethane	14	0	1430	A	1	102.0	374.2	40.6	10.1	-2.11	HFC
R-152a	1,1-difluoroethane	Ethane	1.4	0	124	A	2	66.0	386.4	45.2	9.1	-1.74	HFC
R-227ea	1,1,1,2,3,3,3-Heptafluoropropane	Propane	34.2	0	3220			170.0	374.9	29.3	7.0	0.06	HFC
R-236ea	1,1,1,2,3,3-Hexafluoropropane	Propane						152.0	412.4	35.0	3.4	0.75	HFC
R-236fa	1,1,1,3,3,3-hexafluoropropane	Propane	240	0	9810	A	1	152.0	398.1	32.0	4.4	0.54	HFC
R-245ca	1,1,2,2,3-Pentafluoropropane	Propane	6.2	0	693			134.1	446.6	39.3	1.7	0.70	HFC
R-245fa	1,1,1,3,3-pentafluoropropane	Propane	7.6	0	1030	B	1	134.0	427.2	36.5	2.5	0.56	HFC
R-1234ze	1,3,3,3-tetrafluoropropene	Propene						114.0	382.5	36.4	7.6	-0.33	HFO
R-1234yf	2,3,3,3-Tetrafluoropropene	Propene			4			114.0	367.9	33.8	10.1	NaN	HFO
R-600	Butane	Hydrocarbons		0	1	A	3	58.1	425.1	38.0	3.8	1.11	HC
R-600a	Isobutane	Hydrocarbons	0.41	0	20	A	3	58.1	407.8	36.3	5.3	0.90	HC
R-601	Pentane	Hydrocarbons				A	3	72.2	469.7	33.7	1.2	1.75	HC
R-601a	Isopentane	Hydrocarbons	0.018	0	20	A	3	72.2	460.4	33.8	1.5	0.85	HC
R-C318	Octafluorocyclobutane	Cyclic Organic Compounds	0.01	0	1	A	1	200.0	388.4	27.8	4.9	0.84	PFC

Table 2. Screened working fluids.

	T_1 (K)	P_1 (bar)	PR (-)	P_2 (bar)	ΔT_{sh} (K)	PP_E (K)	PP_C (K)	\dot{m} (kg/s)	η (%)	W_p (kW)	W_e (kW)	D (mm)	N (RPM)	A_E (m ²)	A_C (m ²)	$D_{i,h}$ (mm)	$D_{o,h}$ (mm)	$D_{i,c}$ (mm)	$D_{o,c}$ (mm)
R123	314.12	1.60	3.10	4.94	0.00	13.59	13.05	0.50	7.88	0.17	7.52	65.74	40700	2.22	4.59	28.31	45.55	46.29	71.06
R124	313.29	5.96	2.84	16.94	0.01	12.99	11.37	0.64	7.85	0.77	8.52	39.72	63437	1.97	3.70	25.04	43.05	37.34	63.64
R141b	313.32	1.34	3.17	4.23	0.00	13.58	12.39	0.37	8.15	0.13	7.55	65.59	47369	2.05	3.96	27.45	45.16	43.38	68.18
R142b	314.17	5.38	2.68	14.42	0.01	12.80	12.40	0.45	7.83	0.55	8.06	38.49	75480	1.77	2.83	23.80	41.81	33.64	59.78
R227ea	316.44	7.68	2.73	20.94	0.00	13.83	13.78	0.92	6.84	1.32	8.66	40.51	52275	2.19	3.38	27.18	45.87	38.69	63.85
R236ea	314.97	3.57	2.93	10.45	0.00	13.59	13.65	0.57	7.45	0.41	7.75	47.86	52979	1.96	4.09	25.48	43.26	41.54	66.95
R236fa	315.48	4.69	2.83	13.25	0.01	13.69	13.79	0.64	7.29	0.60	7.89	44.24	54879	1.87	3.61	25.16	42.87	39.53	64.85
R245ca	314.79	1.83	3.18	5.83	0.00	13.07	13.46	0.44	7.70	0.19	7.63	59.20	48664	2.05	4.33	26.41	44.02	44.17	69.02
R245fa	314.86	2.65	3.09	8.18	0.01	13.13	13.48	0.47	7.67	0.29	7.70	50.99	54881	1.95	3.90	25.37	43.18	40.93	67.04
R1234ze	315.34	8.13	2.66	21.64	0.01	13.55	12.78	0.60	7.26	1.04	8.36	34.77	74034	1.59	2.40	23.55	41.18	32.05	57.77
BUTANE	314.90	3.97	2.61	10.38	0.00	12.94	13.38	0.25	7.60	0.41	7.83	38.67	100088	1.51	2.84	22.04	40.11	33.84	60.39
IBUTAN	314.42	5.49	2.57	14.11	0.03	12.12	12.34	0.29	7.64	0.66	8.46	35.41	105982	1.74	3.19	22.49	41.04	33.75	60.71
PENTANE	314.75	1.22	3.02	3.68	0.04	13.53	13.70	0.23	7.62	0.14	7.45	62.82	62139	1.71	3.77	25.20	42.48	42.92	67.34
ISOPENTANE	311.81	1.45	3.28	4.76	2.00	15.35	12.63	0.21	8.30	0.17	7.22	53.81	75089	1.35	4.12	22.83	40.04	41.49	67.11
RC318	314.21	5.07	3.16	16.03	0.01	11.72	13.42	0.83	7.60	0.91	8.65	44.89	49463	2.52	5.17	27.45	45.62	44.78	70.72
R134a	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*
R152a	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*
R1234yf	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*

Table 5. ORC sizing optimisation results.

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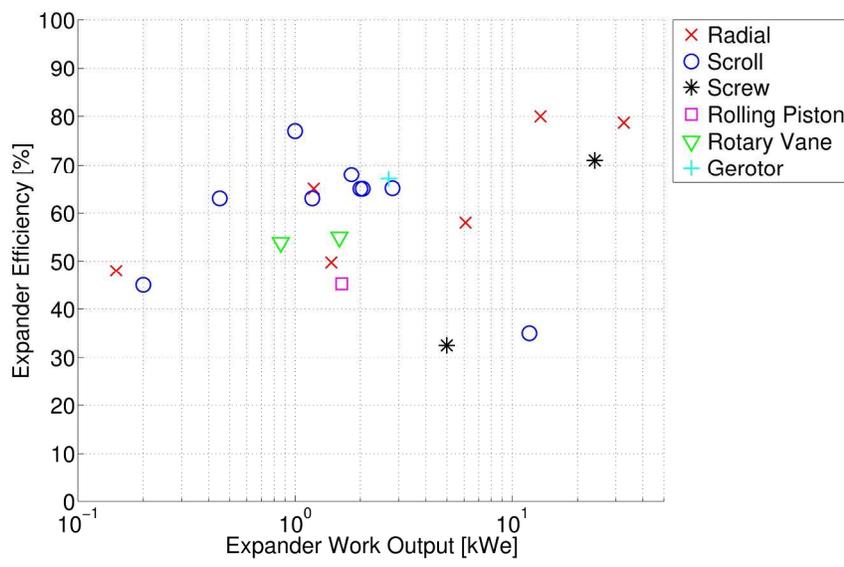


Figure 1. Literature review of current small scale low temperature experimental ORC expanders. 232x138mm (300 x 300 DPI)

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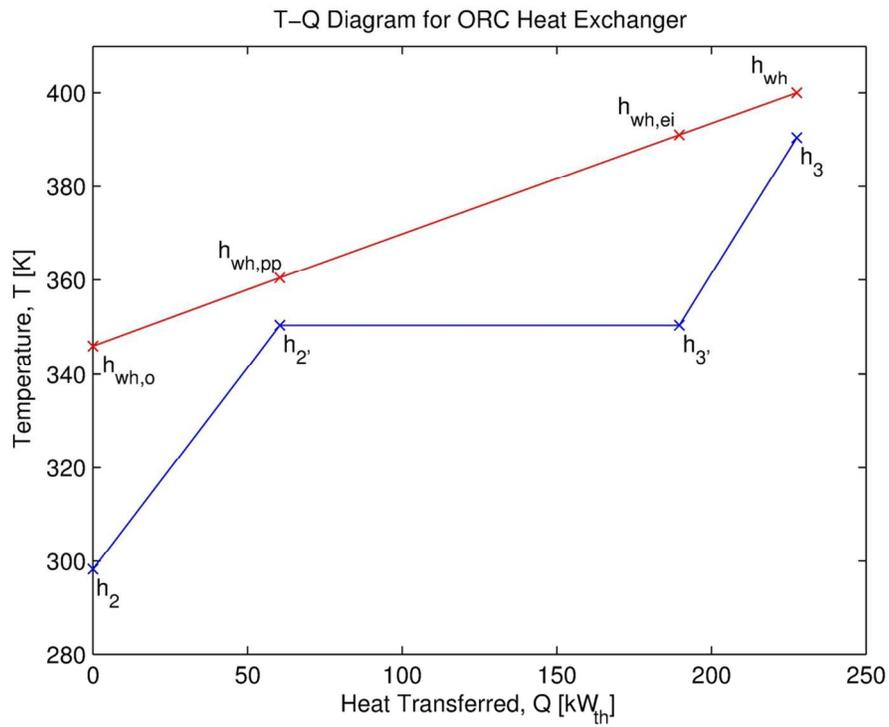


Figure 2. Schematic of the temperature distribution and heat transfer process between the heat source (top line) and the working fluid (bottom line) in a typical ORC evaporator. 111x83mm (300 x 300 DPI)

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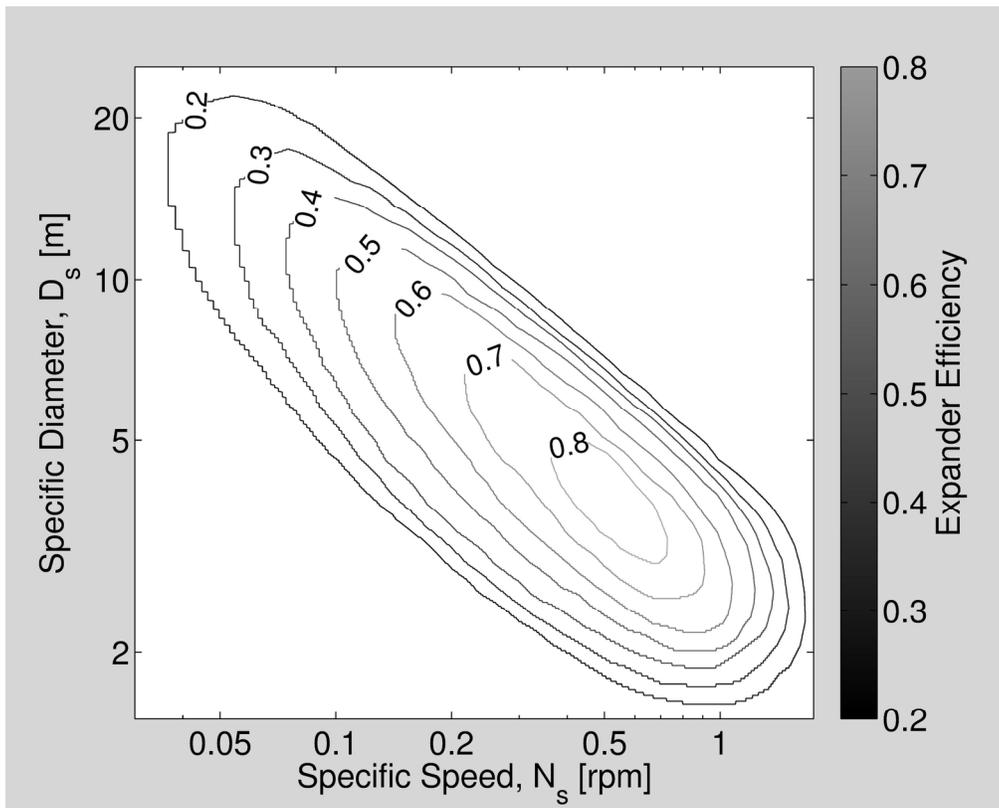


Figure 3. Digitisation of obtainable efficiency contours for radial inflow turbines correlated against specific speed and specific diameter by Watson & Janota.³⁵
156x127mm (300 x 300 DPI)

view

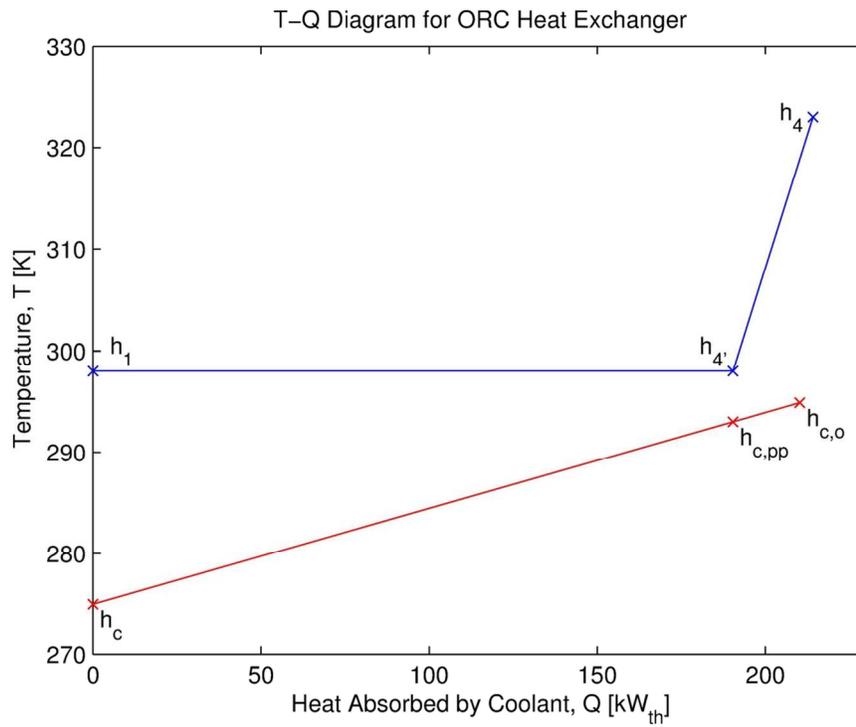


Figure 4. Schematic of the temperature distribution and heat transfer process between the heat sink (bottom line) and the working fluid (top line) in a typical ORC condenser. 111x83mm (300 x 300 DPI)

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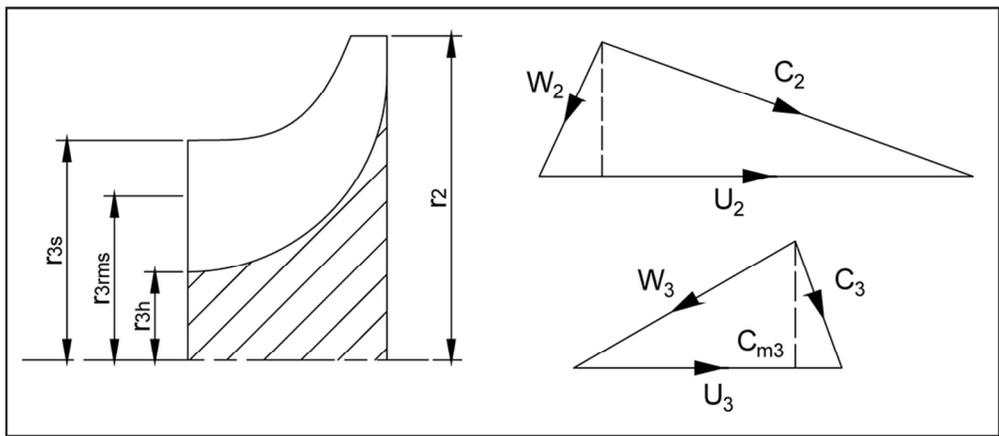


Figure 5. Radial turbine rotor geometry viewed from the meridional plane (left), and rotor inlet (top right) and rotor outlet (bottom right) velocity triangles. C and W correspond to absolute and relative velocity respectively.

89x39mm (300 x 300 DPI)

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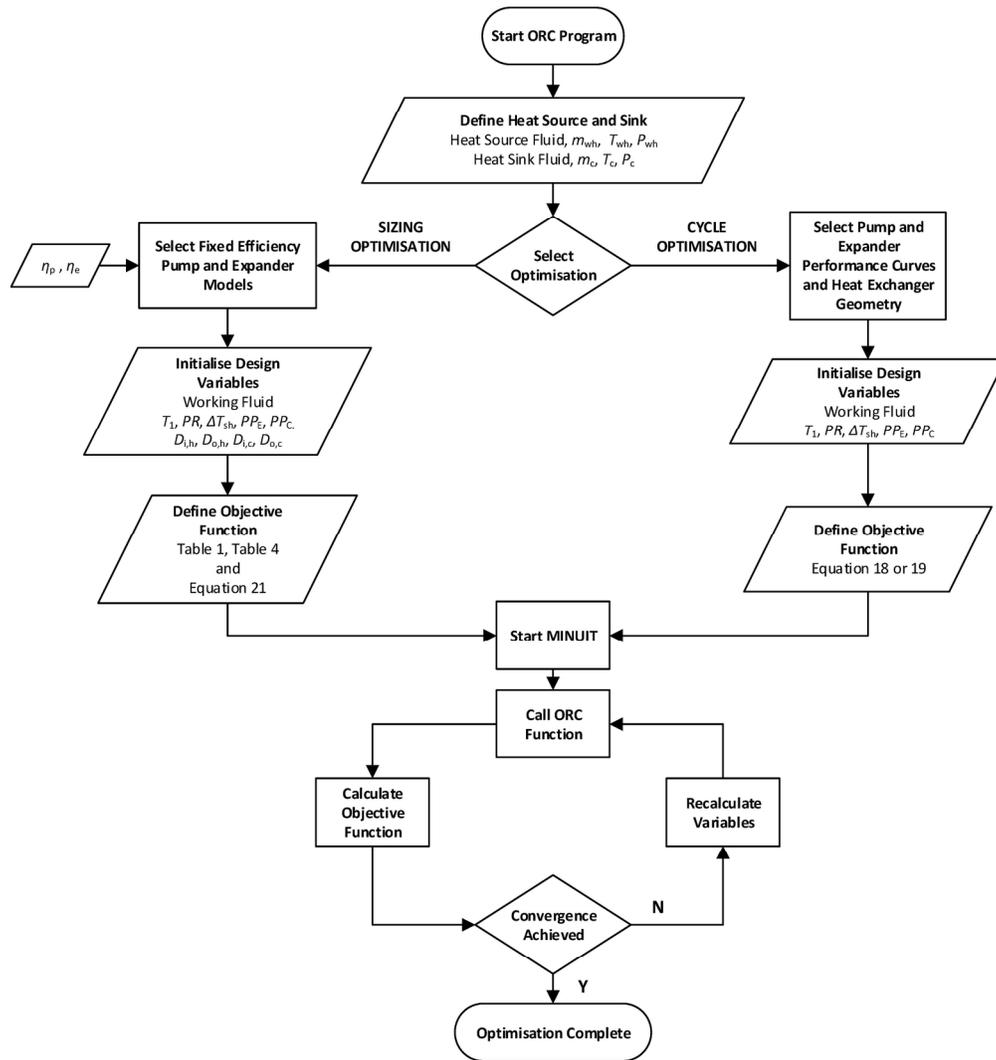


Figure 6. The optimisation strategy employed within the ORC program for both sizing and cycle optimisation. 186x198mm (300 x 300 DPI)

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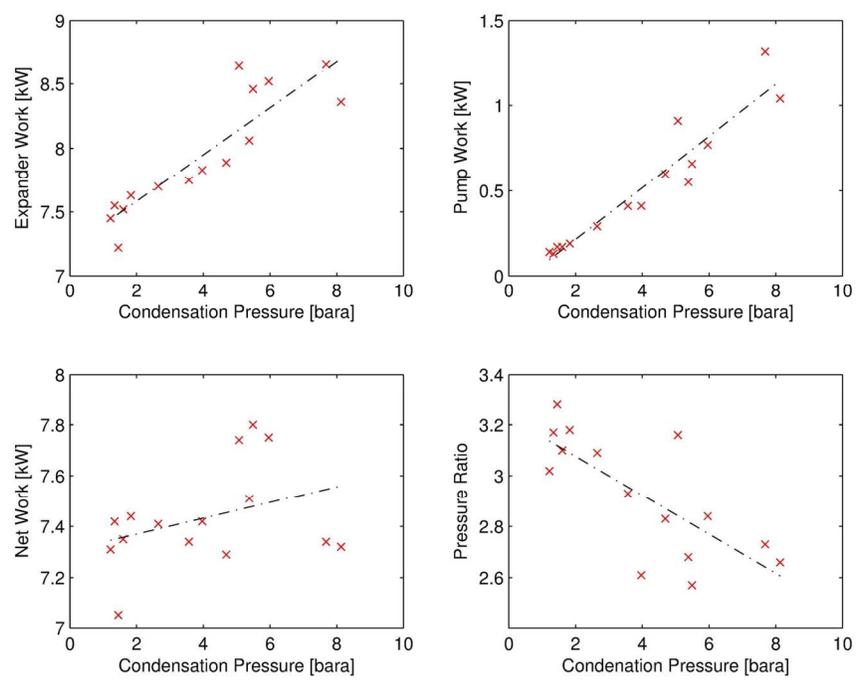


Figure 7. Variation in ORC performance with condensation pressure resulting from the sizing optimisation.
(a) expander work (b) pump work (c) net work (d) pressure ratio.
148x111mm (300 x 300 DPI)

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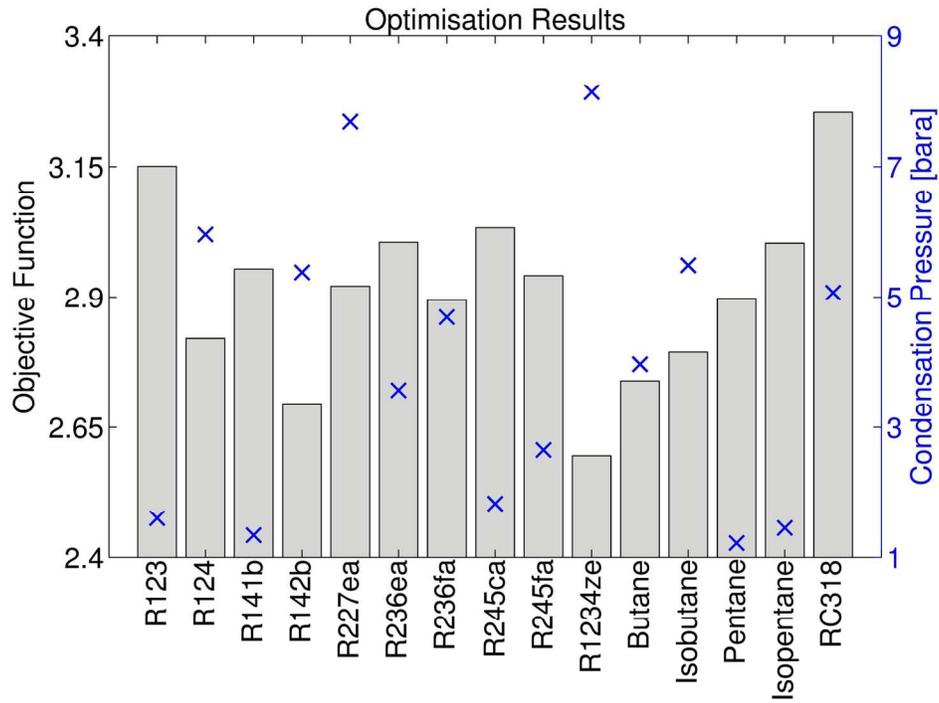


Figure 8. Sizing optimisation results for the 15 working fluids considered. (Bars indicate the objective function value (Equation 21) and the crosses indicate condensation pressure).
148x111mm (300 x 300 DPI)

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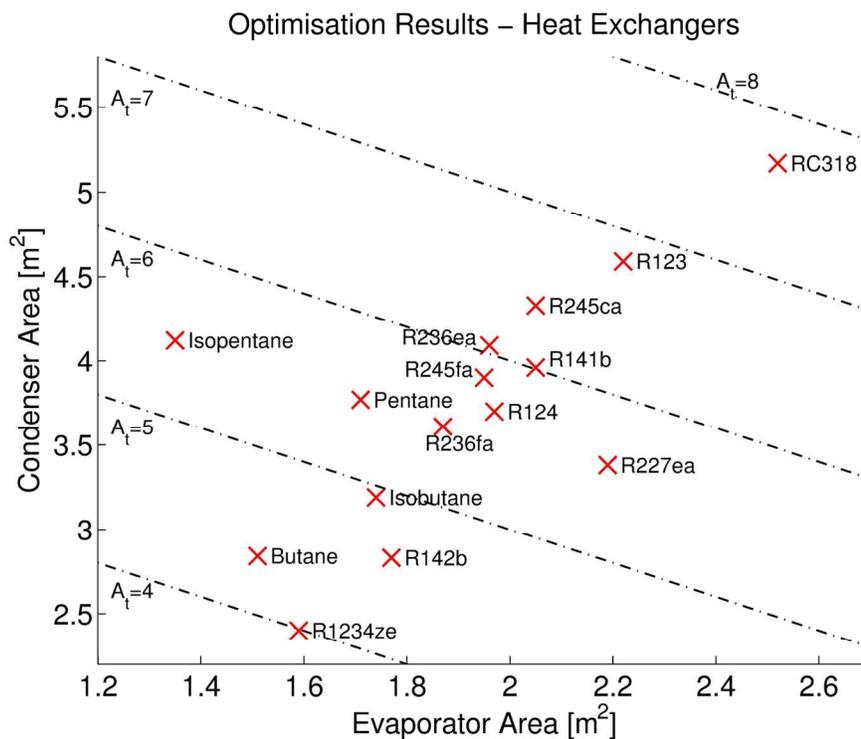


Figure 9. Evaporator and condenser areas that resulted from the sizing optimisation for the 15 working fluids considered.

148x111mm (300 x 300 DPI)

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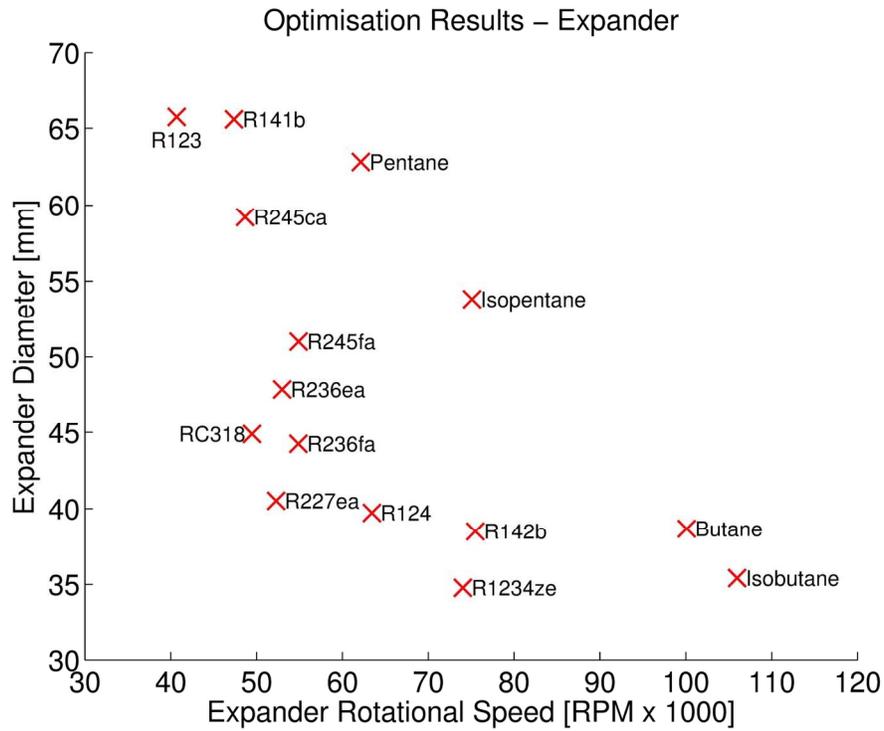


Figure 10. Expander rotational speed and rotor diameter required for the optimised cycles that resulted from the sizing optimisation.
148x111mm (300 x 300 DPI)

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