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Optimal Taxation of Asset Income with Endogenous
Government Consumption: Theory, Estimation and
Welfare

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Optimal Taxation of Asset Income with Endogenous Government Consumption: Theory, Estimation and Welfare

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Abstract

This paper derives the Ramsey optimal policy for taxing asset income in a model where government expenditure is a function of net output or the inputs that produce it. Extending Judd (1999), I demonstrate that the canonical result that the optimal tax on capital income is zero in the medium to long term is a special case of a more general model. Employing a vector error correction model to estimate the relationship between government consumption and net output for the United States between 1947Q1 to 2013Q2, I demonstrate that this special case is empirically implausible, and show how the cointegrating vector can be used to determine the optimal tax schedule. I simulate a version of the model using the empirical estimates to measure the welfare implications of changing the tax rate on asset income, and contrast these results with those generated in a version of the model where government consumption is purely exogenous. The shifting pattern of welfare measurements confirms the theoretical results. Given that the prevailing tax rate on asset income in the US is measured at 0.441, abolishing the tax completely still generates welfare improvements, though only by the equivalent of less than a one percent permanent increase in consumption—less than a third the implied welfare benefit when the endogeneity of the government consumption is ignored. The maximum welfare improvement from shifting part of the burden of tax from capital to labour is the equivalent of a permanent increase in consumption of between only 1.173 and 1.304% and is attained when the tax on asset income is lowered to between 0.18 and 0.2. Allowing the tax rate to vary over time raises the maximum welfare benefit to 1.31%. All the results are very robust to a wide range of elasticities of labour supply.

JEL classification: E62, H62

Keywords: Fiscal Policy; Optimal Capital Taxation; Vector Error Correction Model

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1 Introduction

If governments must fund their activities by taxing income, on which sources of income should the burden fall? In this paper I consider a general optimal growth model, one in which there is a direct link between either aggregate net output or the factor inputs that produce it, and the share of output allocated to government consumption. In such an economy the canonical results of zero taxation of capital income no longer hold. I demonstrate that for an empirically plausible specification of the link between government consumption and net output, there is a simple relationship that can be employed to determine the optimal rate of tax on asset income and estimate a range of appropriate rates for the United States. Finally, I measure the welfare implications of shifting the burden of taxation between asset income and labour earnings. I demonstrate that the optimal tax rate on asset income is indeed positive, but that given the prevailing rates of taxation in the United States, the maximal welfare benefit that can be obtained from adopting an optimal policy is much smaller than what usually emerges when government consumption expenditure is assumed to be exogenously determined.

Atkinson and Stiglitz (1976) demonstrated how the optimal rate of tax on interest income, depends on the complementarity or substitutability between consumption and leisure in a representative agent's instantaneous utility function. Additive separability between the two, implies the optimal tax rate on interest is zero. Chamley (1981) was the first to calculate the excess burden associated with the taxation of income from endogenously determined capital in a complete general equilibrium setting. Judd (1985) and Chamley (1986) extended this work and demonstrated that in standard optimal growth models, models where capital and consumption converge to a steady state, the optimal long-run policy sets the tax rate on income from capital to zero. Judd (1999) showed that for a wider class of dynamic models, particularly models that do not necessarily converge to a single steady state or balanced growth path, optimal policy still entails setting the tax rate on capital income to at least an average of zero over time.

In Chamley (1981), (1986), and Judd (1985), taxes are imposed to finance a fixed amount of government expenditure. By contrast, in Judd's (1999) more general formulation, government expenditure is a public good that enters the utility function of the representative agent. In none of this work is government expenditure directly related to economic output or its production. In Section 2, I adopt Judd's (1999) approach to determining optimal fiscal policy in models that may not necessarily possess a single steady state or balanced growth path, but I introduce government consumption as, first, a general function of factor inputs, and then more specifically as a function of the economic output they generate. Zero taxation of asset income does not emerge here as an optimal policy except as a special case. Instead, if we assume that government expenditure and domestic output, net of depreciation, are related to each other in a particular way—one that can be easily estimated as a cointegrating vector—a simple formula for the optimal tax rate on asset income emerges.

Consider the behaviour of government consumption expenditure and net domestic product in the United States from 1947 onward in Figure 1. Throughout this work I use nominal data deflated by the net domestic product deflator—the focus here is on the financing of government

consumption expenditure, so real volume measures of government outputs would generate a distorted picture of how much net output is devoted to government consumption. The growth of government expenditure seems to track the growth of net domestic product over the same period, an impression that is reinforced if we consider either their ratio or the ratio of their trend components in Figure 2. In Section 3, I demonstrate that both are integrated series and that there exists a cointegrating relationship between them that can be captured by estimating a vector error correction model. Furthermore, forecasts generated by this very same vector error correction model can then be used to provide an estimate of the long-run optimal tax rate on asset income.

Finally in Section 4, I incorporate the estimates from Section 3 into the calibration of an optimal growth model with elastic labour supply and measure the welfare implications of shifting the tax burden from income derived from assets to labour earnings. As has been demonstrated in previous studies, the prevailing rate of tax on asset income is sufficiently high in the United States that eliminating it completely and shifting the burden to labour income generates a positive welfare benefit. However, this benefit is much smaller than what usually emerges because ordinarily it is assumed that the evolution of government consumption flows are not directly related to the overall size of the economy. Rather than eliminating the tax completely, a more modest shift, one that lowers the tax rate on asset income from its recent long-run average of 0.441 to between 0.18 and 0.2 (depending on the estimates chosen), generates the greatest (though still relatively modest) improvement in welfare, equivalent to a permanent increase in consumption of between 1.173% and 1.304%. These numbers can be improved upon, though only to a very small extent, if the tax rate is permitted to shift slightly over time in the vicinity of this range.

As far back as Adolph Wagner (1883) and Henry Carter Adams (1898), Economists, have postulated a close relationship between the amount of government expenditure and the overall size of the economy. Indeed, a sizable empirical literature has developed to examine and explain this relationship, starting with the seminal work by Peacock and Wiseman (1961) for the United Kingdom. Yet rarely is this feature incorporated into models studying optimal fiscal policy. Taken together, the theoretical and empirical results of this work suggest that failure to consider the relationship between the government activity taxes help finance and the overall size and productive capacity of the economy in general has the potential to skew our conclusions regarding the best allocation of the tax burden across the different input factors.

In 1990, Robert E. Lucas wrote:

When I left graduate school, in 1963, I believed that the single most desirable change in the U.S. tax structure would be the taxation of capital gains as ordinary income. I now believe that neither capital gains nor any of the income from capital should be taxed at all.

Yet the continued development of dynamic general equilibrium models that endogenise the supply of capital has not settled the argument regarding the efficacy of taxing the income it

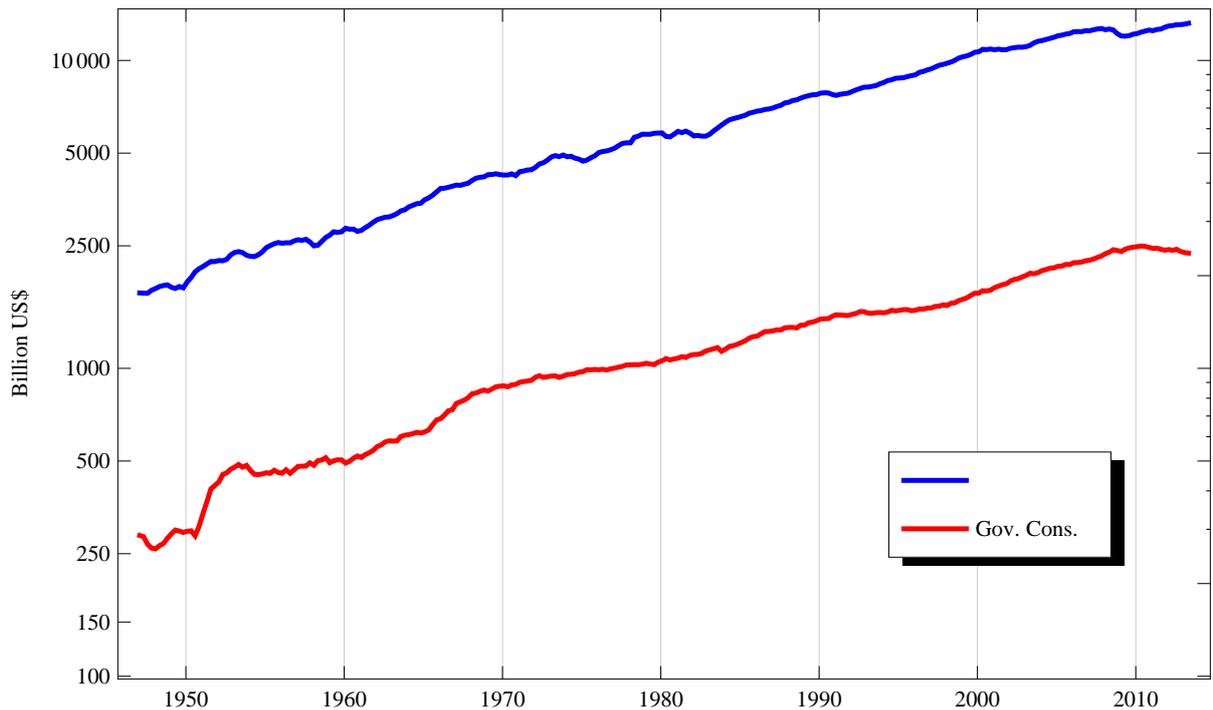


Figure 1: Net domestic product and government consumption, quarterly in the United States, seasonally adjusted annual rate deflated by the NDP deflator, 1947Q1 to 2013Q2, natural logarithmic scale. *Data Source:* Federal Reserve Economic Data, Federal Reserve Bank of St. Louis; U.S. Department of Commerce: Bureau of Economic Analysis variables: Net Domestic Product [A362RC1Q027SBEA], Government Consumption Expenditures [A955RC1Q027SBEA], Deflator [A362RG3Q086SBEA]; <http://research.stlouisfed.org/fred2/>.

generates. Aiyagari (1995), Correia (1996), Reis (2011) and others, all find that under conditions of uninsurable idiosyncratic risk, asymmetric information, or the inability of governments to tax some factor inputs, Ramsey optimal policies will include some taxation of capital income. This work implies that even in the absence of these sorts of frictions, imposing some of the burden of funding government expenditure on capital income can be economically efficient, provided there is a functional relationship between government consumption, the capital stock and the overall size of the economy. Indeed, rather than setting the tax rate on asset income to zero, a welfare optimising policy for the United States would imply the near equalising of tax rates across different sources of income. The only difference between the rates of taxation imposed on asset income and earnings will stem from the burden of debt service, which would fall solely on the latter.

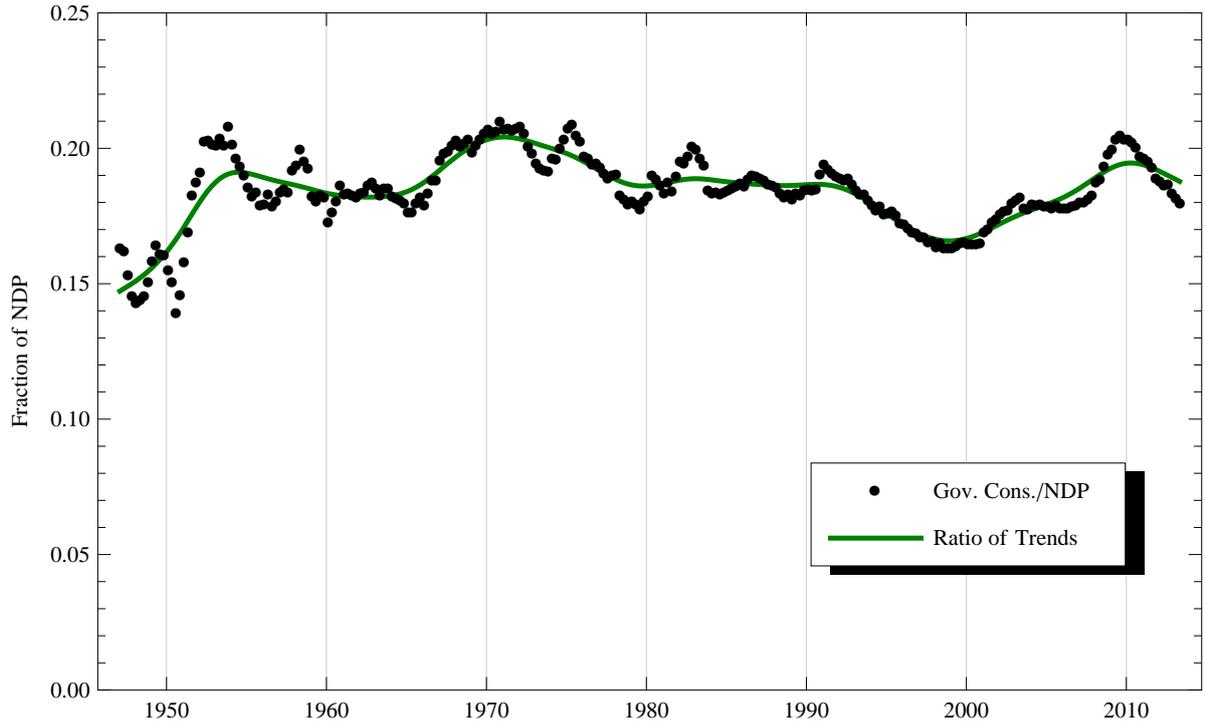


Figure 2: The ratio of Government Consumption Expenditure to Net Domestic Product in the United States, and the ratio of their trend components from Hodrick Prescott Filters (the value of the penalty parameter is set to $\lambda=1600$), 1947Q1 to 2013Q2. *Data Source:* Federal Reserve Economic Data, Federal Reserve Bank of St. Louis; U.S. Department of Commerce: Bureau of Economic Analysis variables: Net Domestic Product [A362RC1Q027SBEA], Government Consumption Expenditures [A955RC1Q027SBEA], Deflator [A362RG3Q086SBEA]; <http://research.stlouisfed.org/fred2/>.

2 The Ramsey Optimal Policy

2.1 The Representative Household's Problem

We begin by reformulating Judd's (1999) optimal taxation argument in discrete time and also alter his model to make government consumption a function of either factor inputs or the net output they together produce. Assume an economy in which all participants are members of households that share the instantaneous utility function $u : \mathbb{R}_+^2 \rightarrow \mathbb{R}$, which maps preferences over consumption and labour, and a discount factor $\beta \in (0, 1)$. Utility is strictly increasing in consumption, and weakly decreasing in labour. Without loss of generality, the initial size of the population is normalised to $N_0=1$, and a representative household chooses its consumption c_t and labour input l_t to maximise its infinite horizon discounted utility:

$$\max_{c,l} \sum_{t=0}^{\infty} \beta^t N_t u [c_t, l_t] \quad (\text{P.1})$$

subject to

$$N_{t+1}a_{t+1} = N_t(\bar{w}_t l_t + (1 + \bar{r}_t) a_t - \bar{p}_t c_t) \quad (1)$$

where a_t represents assets (both bonds and capital); \bar{w}_t , \bar{r}_t and \bar{p}_t represent the time t after tax wage rate, after-tax rate of return on asset holding and after-tax price of consumption; the size of the population is N_t , and the net rate of population growth between time t and $t + 1$ is $N_{t+1}/N_t - 1$.

Differentiating the optimisation problem P.1 with respect to c_t , l_t and a_{t+1} yields the first order conditions

$$u_c [c_t, l_t] - \lambda_t \bar{p}_t = 0, \quad (2)$$

$$u_l [c_t, l_t] + \lambda_t \bar{w}_t = 0, \quad (3)$$

$$-\lambda_t + \beta \lambda_{t+1} (1 + \bar{r}_{t+1}) = 0, \quad (4)$$

where $u_c [c_t, l_t] > 0$ and $u_l [c_t, l_t] < 0$ are the marginal utilities of consumption and labour, and λ_t is a current value costate variable that expresses the marginal utility derived by the representative household from a positive increment to asset wealth.¹

2.2 The Social Planner's Problem

Output in this economy is produced by combining aggregate capital K_t and aggregate effective labour $z_t L_t$, which is the aggregate labour input itself $L_t = N_t l_t$ multiplied by labour augmenting technology z_t . I denote the production function as $F : \mathbb{R}_+^2 \rightarrow \mathbb{R}_+$. Capital depreciates at the constant rate $\delta \geq 0$, and so net domestic product, defined as output net of capital depreciation is $Y_t \equiv F[K_t, z_t L_t] - \delta K_t$. We assume competitive firms maximise profits, so that pre-tax factor returns r_t and w_t equal their marginal products. I also assume the production technology F is homogenous of degree 1, so that in equilibrium:

$$r_t = F_1[K_t, z_t L_t] - \delta, \quad (5)$$

$$w_t = z_t F_2[K_t, z_t L_t]. \quad (6)$$

The government raises revenue in each period t by selling one period bonds B_{t+1} , collecting a tax on labour earnings $\tau_t^l = 1 - \frac{\bar{w}_t}{w_t}$, collecting a tax $\tau_t^a = 1 - \frac{\bar{r}_t}{r_t}$ levied on income from the returns generated by either of the two assets, physical capital or the bonds themselves, and collecting an *ad valorem* tax $\tau_t^c = \frac{\bar{p}_t}{p_t} - 1$ on consumption c_t . In this real economy we normalise the pre-tax price of the consumption good p_t to one. Together all these revenues finance government consumption, which here is confined to that portion of government activity represented on the expenditure side of the national accounts which is not designated as investment, or redeem the interest and principal of all the outstanding debt incurred in the period prior.² In contrast to most of the optimal tax literature, where government consumption is fixed, or Judd (1999), where it enters the utility function of both the representative agent and the social planner, here

¹For the special case where $\forall l, u_l [c, l] = 0$, the first order conditions reduce to (2) and (4) only.

²Adding transfers, provided they are lump-sum, would not alter the results.

I assume that just like output, it is a function of either one or both aggregate inputs, capital and effective labour $G : \mathbb{R}_+^2 \rightarrow \mathbb{R}_+$. The government's budget constraint is

$$B_{t+1} = G[K_t, z_t L_t] - \tau_t^l w_t L_t - \tau_t^a r_t (K_t + B_t) + (1 + r_t) B_t - \tau_t^c C_t, \quad (7)$$

where B_t is the aggregate stock of government bonds at the beginning of time t , and $C_t = N_t c_t$ represents aggregate consumption flows during this period.

Now consider the Ramsey second best problem of a policy maker who chooses per-capita consumption c_t , leisure l_t , the after-tax price of consumer goods \bar{p}_t , and after-tax factor returns \bar{r}_t and \bar{w}_t which maximise the representative households' discounted utility subject to physical feasibility conditions. The incentive compatibility constraints implied by competitive equilibrium:

$$\max_{c, l, \bar{r}, \bar{w}, \bar{p}} \sum_{t=0}^{\infty} \beta^t N_t u [c_t, l_t] \quad (\text{P.2})$$

subject to the incentive compatibility constraints (2) to (4), the feasibility condition:

$$K_{t+1} = F [K_t, z_t L_t] - G [K_t, z_t L_t] + (1 - \delta) K_t - C_t, \quad (8)$$

and assuming the aggregate production function F is homogenous of degree one, the government's budget constraint (7), which can be reformulated as:

$$B_{t+1} = \bar{r}_t (K_t + B_t) + \bar{w}_t L_t + \delta K_t - F [K_t, z_t L_t] + G [K_t, z_t L_t] - (\bar{p}_t - 1) C_t + B_t. \quad (9)$$

I also assume:

$$\lim_{t \rightarrow \infty} |b_t| < \infty \quad (10)$$

$$\bar{r}_t \geq 0 \quad (11)$$

$$\bar{w}_t \geq 0 \quad (12)$$

$$\bar{p}_t \geq 0 \quad (13)$$

The corresponding current value Lagrangian for the policy maker is:

$$\begin{aligned} \mathcal{L}_{SP} = & \sum_{t=0}^{\infty} \beta^t N_t u [c_t, l_t] \\ & + \sum_{t=0}^{\infty} \beta^t \phi_t^k (F [K_t, z_t L_t] - G [K_t, z_t L_t] + (1 - \delta) K_t - C_t - K_{t+1}) \\ & + \sum_{t=0}^{\infty} \beta^t N_t \phi_t^\lambda (\beta \lambda_{t+1} (1 + \bar{r}_{t+1}) - \lambda_t) \\ & + \sum_{t=0}^{\infty} \beta^t \mu_t (\bar{r}_t (K_t + B_t) + \bar{w}_t L_t + \delta K_t - F [K_t, z_t L_t] + G [K_t, z_t L_t] - (\bar{p}_t - 1) C_t + B_t - B_{t+1}) \\ & + \sum_{t=0}^{\infty} \beta^t N_t \phi_t^c (u_c [c_t, l_t] - \lambda_t \bar{p}_t) + \sum_{t=0}^{\infty} \beta^t N_t \phi_t^l (u_l [c_t, l_t] + \lambda_t \bar{w}_t) \\ & + \sum_{t=0}^{\infty} \beta^t N_t \nu_t^r \bar{r}_t + \sum_{t=0}^{\infty} \beta^t N_t \nu_t^w \bar{w}_t + \sum_{t=0}^{\infty} \beta^t N_t \nu_t^p \bar{p}_t. \end{aligned}$$

Differentiating \mathcal{L}_{SP} with respect to \bar{p}_t , \bar{w}_t , \bar{r}_t , λ_t , and the per-capita values c_t , l_t , k_{t+1} , and b_{t+1} yields the first order conditions associated with the optimisation problem P.2:

$$u_c [c_t, l_t] - \phi_t^k + \phi_t^c u_{cc} [c_t, l_t] + \phi_t^l u_{lc} [c_t, l_t] - \mu_t (\bar{p}_t - 1) = 0, \quad (14)$$

$$u_l [c_t, l_t] + z_t \phi_t^k (F_2 [K_t, z_t L_t] - G_2 [K_t, z_t L_t]) + \mu_t (\bar{w}_t - z_t F_2 [K_t, z_t L_t] + z_t G_2 [K_t, z_t L_t]), \\ + \phi_t^c u_{cl} [c_t, l_t] + \phi_t^l u_{ll} [c_t, l_t] = 0, \quad (15)$$

$$-\mu_t \frac{c_t}{p_t} - \phi_t^c \lambda_t + \nu_t^p = 0, \quad (16)$$

$$\mu_t l_t + \lambda_t \phi_t^l + \nu_t^w = 0, \quad (17)$$

$$\phi_{t-1}^\lambda N_{t-1} \lambda_t + \mu_t (K_t + B_t) + N_t \nu_t^r = 0, \quad (18)$$

$$N_{t-1} \phi_{t-1}^\lambda (1 + \bar{r}_t) - N_t (\beta \phi_t^\lambda + \phi_t^c \bar{p}_t - \phi_t^l \bar{w}_t) = 0, \quad (19)$$

$$-\phi_t^k + \beta \phi_{t+1}^k (F_1 [K_{t+1}, z_{t+1} L_{t+1}] - G_1 [K_{t+1}, z_{t+1} L_{t+1}] + 1 - \delta) \\ + \beta \mu_{t+1} (\bar{r}_t + \delta - F_1 [K_{t+1}, z_{t+1} L_{t+1}] + G_1 [K_{t+1}, z_{t+1} L_{t+1}]) = 0, \quad (20)$$

$$-\mu_t + \beta \mu_{t+1} (1 + \bar{r}_{t+1}) = 0. \quad (21)$$

In what follows I will focus on interior solutions to (14) to (21) and assume throughout that $\nu_t^r = \nu_t^p = \nu_t^w = 0$.

In the absence of any tax distortions, the marginal value at time t of an increment of capital for the representative household, $\lambda_t > 0$ is equal to its marginal value for the social planner, $\phi_t^k > 0$. Similarly, in a model in which taxes are not distortionary and do not generate excess burdens, Ricardian equivalence prevails, and the neutrality of public debt held in household asset portfolios implies that $\mu_t = 0$. Otherwise, as is the case here, servicing any increase in the public debt burden entails deadweight losses so that $\mu_t < 0$. Following Judd (1999), I define $\Lambda_t \equiv \frac{1}{\bar{p}_t} \frac{\phi_t^k - \mu_t}{\lambda_t}$, which is a measure of the social value of an increment to physical capital when the value of private assets (comprising both capital and public debt) is held constant, and the reciprocal of \bar{p}_t corrects for the distorting effect of ad-valorem taxes paid on private consumption. Again, in a model without distortionary taxation, $\bar{p}_t = 1$, $\phi_t^k = \lambda_t$ and $\mu_t = 0$ so therefore $\Lambda_t = 1$.

Judd (1999) assumes that government expenditure enters the utility function as a way to ensure that the value of $\Lambda_t > 0$. It is, however, possible to achieve the same result by placing a few restrictions on preferences and on the production and government consumption functions.

Lemma 1. *A sufficient condition that ensures that $\Lambda_t > 0$ is $u_l [c_t, l_t] + l u_{ll} [c_t, l_t] + c u_{cl} [c_t, l_t] \leq 0$ and $z_t (F_2 [K_t, z_t L_t] - G_2 [K_t, z_t L_t]) > 0$.*

Proof. Solving (15) for ϕ_t^k , subtracting μ_t , and substituting the interior solutions for (16) and (17) for ϕ_t^c and ϕ_t^l (with $\nu_t^p = \nu_t^w = 0$) yields:

$$\phi_t^k - \mu_t = \frac{-u_l [c_t, l_t] - \mu_t \bar{w}_t + \frac{\mu_t}{\lambda_t} u_{cl} [c_t, l_t] c_t + \frac{\mu_t}{\lambda_t} u_{ll} [c_t, l_t] l_t}{z_t (F_2 [K_t, z_t L_t] - G_2 [K_t, z_t L_t])}. \quad (22)$$

Replacing \bar{w}_t using (3) yields:

$$\frac{\partial H}{\partial l_t} : \phi_t^k - \mu_t = \frac{-u_c [c_t, l_t] u_l [c_t, l_t] + \mu_t (u_l [c_t, l_t] + l_t u_{ll} [c_t, l_t] + c_t u_{cl} [c_t, l_t])}{u_c [c_t, l_t] z_t (F_2 [K_t, z_t L_t] - G_2 [K_t, z_t L_t])}. \quad (23)$$

From the assumptions that $u_c [c_t, l_t] > 0$ and $u_l [c_t, l_t] \leq 0$, $\phi_t^k - \mu_t > 0$ if $u_l [c_t, l_t] + l_t u_{ll} [c_t, l_t] + c_t u_{cl} [c_t, l_t] \leq 0$ and $z_t (F_2 [K_t, z_t L_t] - G_2 [K_t, z_t L_t]) > 0$. Finally from (2) $\lambda_t > 0$ and hence $\Lambda_t > 0$. \square

The value of Λ_t evolves over time according to:

$$\frac{\Lambda_{t+1}}{\Lambda_t} = \frac{\bar{p}_t \lambda_t}{\bar{p}_{t+1} \lambda_{t+1}} \frac{\phi_{t+1}^k - \mu_{t+1}}{\phi_t^k - \mu_t}. \quad (24)$$

Substituting (4) yields:

$$\frac{\Lambda_{t+1}}{\Lambda_t} = \beta (1 + \bar{r}_{t+1}) \frac{\bar{p}_t}{\bar{p}_{t+1}} \frac{\phi_{t+1}^k - \mu_{t+1}}{\phi_t^k - \mu_t}, \quad (25)$$

and then after substituting (20) and (21):

$$\frac{\Lambda_{t+1}}{\Lambda_t} = \frac{\bar{p}_t}{\bar{p}_{t+1}} \frac{1 + \bar{r}_{t+1}}{1 + F_1 [K_{t+1}, z_{t+1} L_{t+1}] - G_1 [K_{t+1}, z_{t+1} L_{t+1}] - \delta}. \quad (26)$$

The numerator in the right-hand side of (26), $1 + \bar{r}_{t+1}$ when multiplied by the price ratio $\frac{\bar{p}_t}{\bar{p}_{t+1}}$, is the cost agents in this economy face when they shift a unit of consumption between period t and $t + 1$. The denominator reflects the cost of this shift in terms of production, which here includes the portion of extra output lost to additional government expenditure. Iterating (26) from period t backwards:

$$\frac{\Lambda_t}{\Lambda_0} = \frac{\bar{p}_0}{\bar{p}_t} \prod_{i=1}^t \frac{1 + \bar{r}_i}{1 + F_1 [K_i, z_i L_i] - G_1 [K_i, z_i L_i] - \delta}. \quad (27)$$

Assume that along a balanced growth path the ad valorem tax rate on consumption is constant so that $\bar{p}_t = \bar{p}_0$. Comparing the growth rates for the costate variables μ_t and λ_t in (4) and (21), we know the ratio μ_t/λ_t is always constant. If this economy converges to a steady state or a balanced growth path, once convergence is complete, the ratio ϕ_t^k/λ_t will have converged to a constant value as well. Hence for an economy that has converged, a solution to the social planner's problem implies the value Λ_t is a constant and (27) implies that the ratio Λ_t/Λ_0 is equal to one.

Theorem 1. *Suppose an economy converges to a steady state or balanced growth path, then assuming an interior solution for (14) to (21), the long-run optimal policy is to set \bar{r} equal to $\lim_{t \rightarrow \infty} F_1 [K_i, z_i L_i] - G_1 [K_i, z_i L_i] - \delta$. The social planner accomplishes this by setting the long-run tax rate τ^a equal to $\lim_{t \rightarrow \infty} G_1 [K_t, z_t l_t] / (F_1 [K_t, z_t l_t] - \delta)$.*

Proof. Follows from $\Lambda_t/\Lambda_0 = 1$ in (27). \square

The results in Theorem 1 do not depend on the distorting properties of the other taxes. Indeed, notice how the same trajectory of Λ_t/Λ_0 can be generated by choosing either the sequence $\{1 + \bar{r}_i\}_{i=1}^t$ or the ratio $\frac{\bar{p}_0}{\bar{p}_t}$. So in general the social planner has more policy instruments than necessary to achieve an optimal solution to P.2.

Corollary 1. *The availability of a consumption tax is not necessary to ensure a Ramsey second best allocation associated with the optimisation problem P.2.*

Proof. From (4) and (21) we know that $\frac{\mu_{t+1}}{\lambda_{t+1}} = \frac{\mu_t}{\lambda_t} \forall t$. Combining (18) with (19) and inserting the values of K_{t+1} and B_{t+1} from (8) and (9) yields:

$$\frac{\mu_t}{\lambda_t} (\bar{w}_t l_t - c_t) - \phi_t^c + \phi_t^l \bar{w}_t = 0.$$

Combining this with (17) while assuming an interior solution so that $\nu_t^w = 0$ yields:

$$\phi_t^c = -\frac{\mu_t}{\lambda_t} c_t,$$

which replicates (16) as long as $\nu_t^p = 0$. Since (16) is implied by the other first order conditions, for any interior solution the availability to the social planner of a consumption tax does not alter the result in Theorem 1. \square

In what follows, we assume that \bar{p}_t is always constant. A number of special cases emerge from Theorem 1, depending on how the function G is specified. For example, if $G_1 [K_t, z_t L_t] = 0$ so that government consumption is not a function of the capital stock, we recover the canonical Chamley-Judd result of zero taxation on asset income as the long-run optimising policy. This is the case even if $G_2 [K_t, z_t L_t] \neq 0$, and government consumption is still a function of the amount of effective labour employed in production. Alternatively if $G_1 [K_t, z_t L_t] < 0$, then any policy that encourages capital accumulation depresses the amount of output diverted to government consumption, and the optimal policy is to set \bar{r} to be less than r and $\tau^a < 0$. This means that the long-run optimal policy is for the social planner to institute a subsidy for capital income. For example, if $G [K_t, z_t L_t] = g K_t^{-\beta} (z_t L_t)^{1+\beta}$, then even in a model with exponential steady state growth, government expenditure as a share of GDP still converges to a strictly positive amount, and yet the optimal tax is still negative. Finally, if $G_1 [K_t, z_t L_t] > 0$ then the optimal tax rate on asset income is positive. Suppose we specify government consumption to be a power function of net domestic product: $G [K_t, z_t L_t] = g (F [K_t, z_t L_t] - \delta K_t)^\gamma$. Then if $g > 0$ and $\gamma > 0$ the optimal tax rate on asset income will be positive.³

Corollary 2. *Suppose an economy converges to a steady state or balanced growth path. If government consumption is the power function $G [K_t, z_t L_t] = g (F [K_t, z_t L_t] - \delta K_t)^\gamma$, then the long-run optimal policy is to set \bar{r} equal to $\lim_{t \rightarrow \infty} (1 - \gamma G [K_t, z_t L_t] / (F [K_t, z_t L_t] - \delta K_t)) (F_1 [K_t, z_t L_t] - \delta)$ and the optimal long-run tax rate on asset income τ^a is equal to $\lim_{t \rightarrow \infty} \gamma G [K_t, z_t L_t] / (F [K_t, z_t L_t] - \delta K_t)$ or $\lim_{t \rightarrow \infty} \gamma g (F [K_t, z_t L_t] - \delta K_t)^{\gamma-1}$*

Proof. Follows from Theorem 1 and $G_1 [K_t, z_t L_t] = \gamma g (F [K_t, z_t L_t] - \delta K_t)^{\gamma-1} (F_1 [K_t, z_t L_t] - \delta)$ which in turn equals $\gamma G [K_t, z_t L_t] (F_1 [K_t, z_t L_t] - \delta) / (F [K_t, z_t L_t] - \delta K_t)$. Substituting for $G [K_t, z_t L_t]$ yields $\gamma g (F [K_t, z_t L_t] - \delta K_t)^{\gamma-1}$. \square

³Ben-Gad (2003) analyses long-run optimal fiscal policy along a balanced growth path in the context of a two-sector endogenous growth model for the case of $g > 0$ and $\gamma = 0$.

In an economy in which government expenditure is exogenously determined, the long-run supply curve for capital is infinitely elastic at a given interest rate. This is why the distortions associated with policies that lower the after-tax rate of return dominate those that generate changes to the labour supply. By contrast, for the type of economies specified in Theorem 1 and Corollary 2, a change in the tax rate on asset income alters not just the amount of capital available to produce the consumption good, but indirectly affects the overall amount of government consumption, which here does not have the usual lump-sum quality. Instead, government consumption is itself a type of distortion that asset taxation serves to mitigate. This remains the case even if the economic activity from which it is derived necessitates the government's consumption.

Consider the case where the values of z_t and N_t converge to constants, and the economy converges to a stationary steady state. If $g > 0$ and $\gamma > 0$, government consumption converges to a positive share of net output and the optimal long-run tax rate on asset income is the share of government consumption multiplied by γ . By contrast, if we assume z_t and/or N_t are growing, the value of γ must be constrained to be less than or equal to one, to ensure that government consumption does not ultimately exceed net output. If there exists a balanced growth path and $\gamma = 1$, government consumption converges to a positive share of output g , and the long-run optimal policy will be one where the tax rate is positive so that $\tau^a = g$. If, however, $0 < \gamma < 1$, and the aggregate economy is growing, then $\lim_{t \rightarrow \infty} g (F[K_t, z_t L_t] - \delta K_t)^{\gamma-1} = 0$, which means we recover the Chamley-Judd optimal long-run policy of setting $\bar{r} = F_1[K, zL] - \delta$ and $\tau^a = 0$ in the limit—though as I will demonstrate below, until the economy converges, the optimal policy may be very different.

Theorem 1 and Corollary 2 apply to economies that have converged to a balanced growth path. What then should be the policy if the economy does not converge to a balanced growth path but is characterized by cycles, or, alternatively, convergence is achieved only over a very long time horizon. Can we say anything about optimal policy in the interim?

The challenge here is that regardless of what the long-run optimum policy is, during an initial period, the social planner might want to set the value \bar{r}_0 very low to exploit the time-zero inelasticity of capital supply. It is this reasoning that gives rise to the "bang-bang" pattern of optimal taxation first derived by Chamley (1986). This is why, even though the more a sequence of tax rates on asset income causes the value of Λ_t to deviate from one, the more it distorts the economy and generates welfare losses, it is not possible to pin down the initial value of Λ_0 or assume it equals one. Yet if we assume that an optimal programme will seek to minimise distortions beyond an initial period of high taxation, subsequent values of Λ_t must be bounded below and above over time: $\Lambda_\infty < \Lambda < \Lambda^\infty$. Setting the bounds

$$\frac{\Lambda_0}{\Lambda^\infty} \leq \prod_{i=1}^t \frac{1 + F_1[K_i, z_i L_i] - G_1[K_i, z_i L_i] - \delta}{1 + \bar{r}_i} \leq \frac{\Lambda_0}{\Lambda_\infty}, \quad (28)$$

and then rewriting the inequalities in logarithms yields

$$\ln \left(\frac{\Lambda_0}{\Lambda^\infty} \right) \leq \sum_{i=1}^t \ln \left(\frac{1 + F_1[K_i, z_i L_i] - G_1[K_i, z_i L_i] - \delta}{1 + \bar{r}_i} \right) \leq \ln \left(\frac{\Lambda_0}{\Lambda_\infty} \right), \quad (29)$$

which implies that as the value of Λ_t in (27) evolves over a sufficiently long period of time, it must on average be equal to one so that it satisfies (28) and the average distortion measured as deviations from $\Lambda_t = 1$ approaches zero in the limit. Extending Judd (1999), this implies that for all $t_1 \geq 0$, any long-run constant value of \bar{r} must satisfy

$$\lim_{t_2 \rightarrow \infty} \frac{1}{t_2} \sum_{i=t_1}^{t_1+t_2} \ln \left(\frac{1 + F_1 [K_i, z_i L_i] - G_1 [K_i, z_i L_i] - \delta}{1 + \bar{r}} \right) = 0, \quad (30)$$

which in turn implies that if the social planner must choose a particular tax rate, then:

Theorem 2. *Assume there exists an interior solution for (14) to (21), for any $t_1 \geq 0$, if the value of \bar{r} is fixed, then the long-run optimal policy is to set it to satisfy (30).*

Theorem 2 generalises Theorem 1 to economies that may not converge to balanced growth paths or steady states. For example, if the dynamic behaviour of the economy is characterized by permanent cycles, and \bar{r} is to be fixed to any value, it will be optimally so, if on average it equals $F_1 [K_t, z_t L_t] - G_1 [K_t, z_t L_t] - \delta$ and the long-run tax rate τ^a on asset income is set to the average value of $G_1 [K_t, z_t L_t] / (F_1 [K_t, z_t L_t] - \delta)$. If once again we assume that government consumption is a power function, then (30) becomes

$$\lim_{t_2 \rightarrow \infty} \frac{1}{t_2} \sum_{i=t_1}^{t_1+t_2} \ln \left(\frac{1 + (1 - \gamma G [K_i, z_i l_i] / (F [K_i, z_i l_i] - \delta K_i)) (F_1 [K_i, z_i L_i] - \delta)}{1 + \bar{r}} \right) = 0, \quad (31)$$

and we can derive a particular policy.

Corollary 3. *Assume there exists an interior solution for (14) to (21). If government consumption is the power function $G [K_t, z_t L_t] = g (F [K_t, z_t L_t] - \delta K_t)^\gamma$, then for a sufficiently large value of $t_1 \geq 0$, the long-run optimal policy is to set \bar{r} so that it equals the average value of $(1 - \gamma G [K_t, z_t l_t] / (F [K_t, z_t L_t] - \delta K_t)) (F_1 [K_t, z_t L_t] - \delta)$ and the optimal long-run tax rate on asset income τ^a is to set it so that it equals the average value of $\gamma G [K_t, z_t L_t] / (F [K_t, z_t L_t] - \delta K_t)$ which equals $\gamma g (F [K_t, z_t L_t] - \delta K_t)^{\gamma-1}$.*

Yet this leaves the question of what is the best policy if the policy maker is not necessarily constrained to choose fixed values for \bar{r}_t and τ_t^a ?

To avoid the issue of time inconsistency, assume a policy maker commits to an infinite sequence of \bar{r}_t that need not be constant. An infinite number of different sequences satisfy the boundary conditions in (28) and hence also satisfy

$$\lim_{t_2 \rightarrow \infty} \frac{1}{t_2} \sum_{i=t_1}^{t_1+t_2} \ln \left(\frac{1 + F_1 [K_i, z_i L_i] - G_1 [K_i, z_i L_i] - \delta}{1 + \bar{r}_i} \right) = 0. \quad (32)$$

Yet only by committing to a policy of setting \bar{r}_i equal to $F_1 [K_i, z_i L_i] - G_1 [K_i, z_i L_i] - \delta$ and tax rates τ_i^a equal to $G_1 [K_i, z_i L_i] / (F_1 [K_i, z_i L_i] - \delta)$ in each period does a policy maker both satisfy (30) and minimise deviations from $\Lambda_t = 1$.

Theorem 3. For a sufficiently large value of $t_1 \geq 0$, an optimal tax policy for asset income is such that the values of \bar{r}_i are set equal to $F_1 [K_i, z_i L_i] - G_1 [K_i, z_i L_i] - \delta$ so as to satisfy (30) and minimize deviations from $\Lambda_t = 1$. This is accomplished by setting the sequence of tax rates τ_i^a equal to $G_1 [K_i, z_i L_i] / (F_1 [K_i, z_i L_i] - \delta)$.

Proof. Follows from boundary conditions in (28) and the definition of \bar{r}_i . \square

Theorem 3 generalises Theorem 6 in Judd (1999) as well as Theorem 2 above. Once again we focus on the power function.

Corollary 4. Suppose government consumption is a power function of net domestic product

$G [K_t, z_t L_t] = g (F [K_t, z_t L_t] - \delta K_t)^\gamma$. Then for a sufficiently large value $t_1 \geq 1$, an optimal tax policy for asset income is such that the values of \bar{r}_t are set equal to $(1 - \gamma G [K_t, z_t L_t] / (F [K_t, z_t L_t] - \delta K_t)) \times (F_1 [K_t, z_t L_t] - \delta)$ so as to satisfy (30) and minimize deviations from $\Lambda_t = 1$. This is accomplished by setting the sequence of tax rates τ_t^a equal to $\gamma G [K_t, z_t L_t] / (F [K_t, z_t L_t] - \delta K_t)$, which equals $\gamma g (F [K_t, z_t L_t] - \delta K_t)^{\gamma-1}$.

Proof. Follows immediately from Theorem 2. \square

There is an obvious limitation to the practical applicability of Theorem 3 and its Corollary 4—the difficulty in determining the appropriate size of the initial t_1 periods during which the social planner may choose to set the tax rate on asset income very high to exploit the short-term inelasticity in the supply of capital.⁴ Yet regardless of the length of t_1 , we can utilise the intuition that underlies Theorem 3 to generate a useful conjecture about how different tax policies and tax rates are likely to compare.

Conjecture 1. Suppose government consumption is a power function of net domestic product, $G [K_t, z_t L_t] = g (F [K_t, z_t L_t] - \delta K_t)^\gamma$. Then a policy of setting the sequence of tax rates τ_t^a equal to $\gamma G [K_t, z_t L_t] / (F [K_t, z_t L_t] - \delta K_t)$, which equals $\gamma g (F [K_t, z_t L_t] - \delta K_t)^{\gamma-1}$ for all periods $t \geq 0$, strictly dominates a policy of fixing τ^a to any fixed value. Furthermore, if $\gamma = 1$, then the policy of fixing $\tau^a = g$ strictly dominates the policy of fixing τ^a to any value $\tau^a \neq g$.

Corollary 3 indicates how a fixed long-run tax rate on asset income should be set if the relationship between government consumption and net output takes a very particular form, the power function. Corollary 4 indicates, again for the power function, how the tax rate on asset income should evolve when the tax rate is not constrained to be fixed. Finally, setting aside the possibility of employing a “bang-bang” optimal control policy through period t_1 , Conjecture 1 predicts how the welfare effects of different tax policies, if implemented immediately, are likely to compare, and not merely over the long-run. Furthermore, though merely a Conjecture, its implications, particularly for welfare, can be more readily quantified than Theorems 1 to 3. Insights gained from a numerical assessment of Conjecture 1 may help to illuminate some

⁴Chamley (1986) provides one method for approximating t_1 .

of the larger welfare implications associated with Theorems 1 to 3, at least when $G [K_t, z_t L_t]$ corresponds to the power function as in Corollaries 2 to 4.

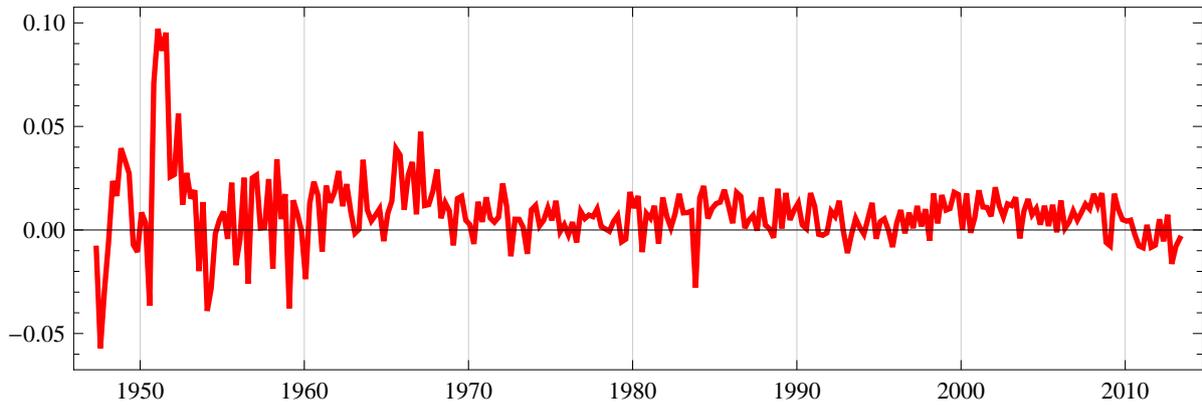
More generally, one possible interpretation of the function $G [K_t, z_t L_t]$, one that generalises beyond the context of the strictly theoretical models considered in this section, is that it expresses a long-run equilibrating relationship between government consumption and either factor inputs or, in the specific case of the power function, the economic output, net of depreciation, they generate. Provided net output and government consumption are integrated $I(1)$ processes, perhaps because they share a trend driven by labour augmenting technology and/or population growth as in the model above, the specific case of the power function is easily estimated, as it corresponds in its logarithmic form to the cointegrating relationship in Johansen’s Vector Error Correction Model (VECM). In the next section I use the VECM to estimate this relationship, and then in Section 4 I incorporate these estimates into the calibration of a model designed to numerically evaluate the main implications of Conjecture 1.

3 An Error Correction Model for Government Consumption in the US

We start by examining the properties of government consumption G_t , and net domestic product in the United States Y_t , using all the available data at the quarterly frequency—from the first quarter of 1947 to the second quarter of 2013. Inspection of the data in Figure 1 and Figure 3 suggests the inclusion of a trend and intercept when testing the data in levels, but only an intercept when testing the data in first differences. In Table 1, neither the augmented Dickey-Fuller, the DF-GLS, the P_T -GLS, or Ng and Perron’s MZ_α , MZ_t , MS_B and MP_t tests can reject the null hypothesis of a unit root at the 1% or 5% critical level when applied to the levels of each series, but all reject the existence of unit roots at the 1% level when applied to the series’ first differences. Indeed, the test for the null hypothesis of a unit root is not rejected for the levels of the series at the 10% critical level, except when the augmented Dickey-Fuller test is applied to government consumption where the p -value is 0.093. For the ratio of the two series (log differences) in the last two columns, the augmented Dickey-Fuller rejects the existence of a unit root at the 5% critical level, as do the DF-GLS, MZ_α , MZ_t , and MP_t at the 10% critical level, while the Kwiatkowski-Phillips-Schmidt-Shin (KPSS) cannot reject the null hypothesis of stationarity of the ratio at the 10% critical value. Similarly, the KPSS test rejects the null hypothesis of stationarity in the levels of each of the two series at the 1% level, but cannot reject the null hypothesis when applied to differences. Together, these results indicate that each of the series can be characterised as a unit root process with drift, and that in concurrence with the intuition derived from Figure 2, their ratio is stationary. A Quandt-Andrews breakpoint test performed on an AR(1) estimation of the log ratio cannot reject the null hypothesis of no breakpoints at a confidence level of 5% when trimming 5, 10 or 15% of the data.

To test for cointegration, I begin by estimating an unrestricted VAR for the two time series. The optimal lag length q for the estimated VAR indicated by the Aikake’s information criterion,

a) Log Government Consumption in the US, First Differences



b) Log Net Domestic Product in the US, First Differences

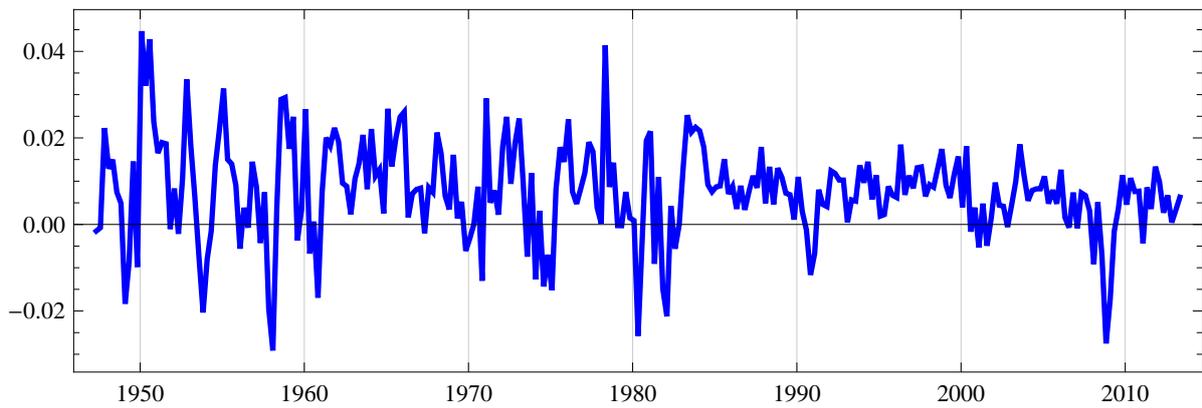


Figure 3: Log differences of net domestic product and government consumption, quarterly in the United States, seasonally adjusted annual rate deflated by the NDP deflator, 1947Q2 to 2013Q2, natural logarithmic scale. *Data Source:* Federal Reserve Economic Data, Federal Reserve Bank of St. Louis; U.S. Department of Commerce: Bureau of Economic Analysis variables: Net Domestic Product [A362RC1Q027SBEA], Government Consumption Expenditures [A955RC1Q027SBEA], Deflator [A362RG3Q086SBEA]; <http://research.stlouisfed.org/fred2/>.

Method	Gov. Consumption		Net Domestic Product		Gov. Cons./NDP	
	Level	First Diff.	Level	First Diff.	Level	First Diff.
ADF	-3.167*	-8.103***	1.954	-10.901***	-3.972**	-8.595***
DF-GLS	-1.395	-4.188***	-1.197	-5.989***	-1.773*	-7.700***
P_T -GLS	25.717	0.583***	21.204	0.346***	4.381	0.296***
MZ_α	-3.947	-28.070***	-4.317	-57.345***	-6.415*	-80.833***
MZ_t	-1.228	-3.746***	-1.201	-5.350***	-1.766*	-6.357***
MS_B	0.311	0.133***	0.278	0.093***	0.275	0.079***
MP_t	21.051	0.874***	32.511	0.439***	3.905*	0.305***
KPSS	0.351†††	0.287	0.368†††	0.334	0.201	0.067

Table 1: Nominal data deflated by NDP deflator, in natural logarithms. ADF is the augmented Dickey–Fuller test. P_T -GLS is the Elliott-Rothenberg-Stock point-optimal test statistic. MZ_α , MZ_t , MS_B , and MP_t are the modified tests in Ng and Perron (2001). KPSS is the Kwiatkowski-Phillips-Schmidt-Shin test. For Government Consumption and Net Domestic Product all tests are conducted with a constant term and trend for levels, and a constant term only for first differences. For the ratio of the two series all tests are conducted with a constant except the ADF test in first differences, which has none. * Reject the null hypothesis of a unit root at the 10% confidence level. ** Reject the null hypothesis of a unit root at the 5% confidence level. *** Reject the null hypothesis of a unit root at the 1% confidence level. ††† Reject the null hypothesis of stationarity at the 1% confidence level.

Akaike’s final prediction error (FPE) and the likelihood ratio (LR) is $q = 6$, but Schwarz’s Bayesian information criterion (SBIC) and the Hannan and Quinn information criterion (HQIC) indicate, as is often the case, a more parsimonious optimal lag length, which here is $q = 2$. If government consumption and net domestic product do indeed share a common stochastic trend, the largest eigenvalue of the system must be equal to one, and to guarantee stability all the others must be (in modulus) less than one. In Figure 8 in the Appendix, I plot the eigenvalues for both values of q . For $q = 2$ [$q = 6$] the largest eigenvalue is .997 [.997], the next highest is .923 [.900], and all the others fall well within the unit circle.

To determine the cointegrating vector itself, I estimate the Vector Error Correction Model (VECM):

$$\begin{aligned} \begin{pmatrix} \Delta \ln G_t \\ \Delta \ln Y_t \end{pmatrix} &= \begin{pmatrix} \alpha_G \\ \alpha_Y \end{pmatrix} (\ln G_{t-1} - \gamma \ln Y_{t-1} - \ln g) \\ &+ \sum_{i=1}^q \begin{pmatrix} \zeta_{GG}(i) & \zeta_{GY}(i) \\ \zeta_{YG}(i) & \zeta_{YY}(i) \end{pmatrix} \begin{pmatrix} \Delta \ln G_{t-i} \\ \Delta \ln Y_{t-i} \end{pmatrix} + \begin{pmatrix} \eta_G \\ \eta_Y \end{pmatrix} + \begin{pmatrix} \varepsilon_{G,t} \\ \varepsilon_{Y,t} \end{pmatrix}, \end{aligned} \quad (33)$$

where α_G and α_Y represent the speed of adjustment, the vector $(1, \gamma)'$ represents the normalised cointegrating vector and g is a constant. If $\gamma = 1$, then the long-run relationship between government consumption and net domestic product is a fixed proportion, represented by the constant term g . Together γ and g correspond to the parameters in the power function that expresses the long-run relationship between government consumption and net output in Section

	Rank	Eigen.	Trace	p -Value	Max-Eigen.	p -Value	SBIC	HQIC
$q=2$	0	0.084	26.650	0.001	23.045	0.002	-11.714	-11.849
	1	0.014	3.605	0.058	2.302	0.058	-11.738	-11.914
$q=6$	0	0.085	25.329	0.001	23.027	0.002	-11.503	-11.716
	1	0.009	2.302	0.129	2.302	0.129	-11.527	-11.765

Table 2: Johansen’s trace and maximum eigenvalue tests along with information criteria for the rank of the matrix $\alpha\beta$

2.

Define the 2×2 matrix $\Phi \equiv \begin{pmatrix} \alpha_G \\ \alpha_Y \end{pmatrix} (1 \quad \gamma)$. From Johansen’s trace and maximum eigenvalue test in Table 2 we reject the null of no cointegrating vector at the 1% confidence level but do not accept the hypothesis of full rank. Similarly, both SBIC and HQIC indicate the rank of Φ is one. Together this implies that $(1, \gamma)'$ represents a valid cointegrating vector that, together with the estimated value of g , represents the long-run relationship between government consumption and net domestic product.

Though the unrestricted vector error correction model (33) is estimated using very different lag lengths q , the estimated values of γ in column (1) of Table 3 are very stable. Indeed, for any choice of lag lengths between $q=2$ and $q=6$, the value of γ varies at most between 0.93 and 0.94. In each case, the value of $\gamma = 1$ falls just outside the 95% confidence interval. Similarly, the p -values in column (2) of Table 3 associated with the test of the null hypothesis of $\gamma = 1$ are 0.052 for $q=2$ and 0.016 for $q=6$. Not surprisingly, when the restriction $\gamma = 1$ is imposed, the estimated value of g equals 0.185, which is close to the mean ratio of government consumption to net domestic output of 0.184 in Figure 2. At the same time, it is much more difficult to reject the null hypothesis that $\alpha_Y = 0$, which implies that net output is weakly exogenous, particularly for the more parsimonious lag structure of $q=2$ in column (3). This restriction on the adjustment coefficient also raises the estimated value of γ to 0.951 for lag lengths of $q=2$ and $q=6$, as well as all values of q in between. Indeed, the confidence interval around its value now includes one. We can reject the null hypothesis of the dual constraints, $\gamma = 1$ and $\alpha_Y = 0$, at the 5% confidence level if $q=6$ in column (4) of Table 3, but not if the values of q are set equal to 2, 3, 4 or 5.

So what do the results in Table 3 tell us about optimal tax policy? First, we cannot conclusively reject the null hypothesis of $\gamma = 1$, at least not for the lag structure of $q=2$. In this case, the optimal long-run tax on asset income is simply equal to the value of g or 0.185. By contrast, if $\gamma < 1$, as the unrestricted estimates imply, and the economy continues to grow in the future, the limiting optimal tax rate as $t \rightarrow \infty$ coincides with the Chamley-Judd rate of zero. Yet immediately setting the rate of tax to zero would not minimise distortions as described in Corollary 4. Even if we believe the estimated power relationship is stable over long periods of

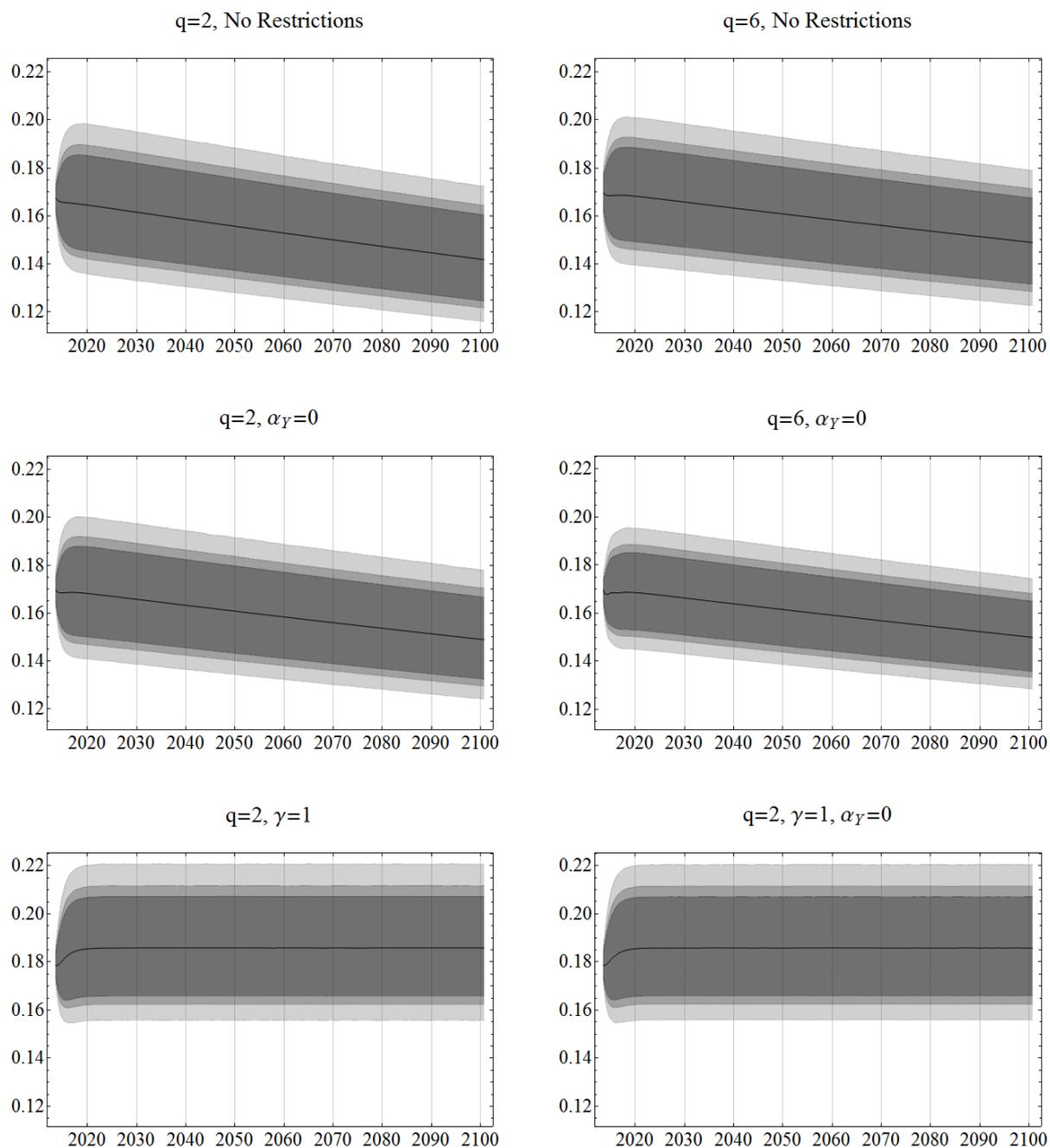


Figure 4: Forecasts for the value of $\gamma G_t / Y_t$ from 2013Q3 to 2100Q4 for the United States derived from the two unrestricted versions of the vector error correction model (33) and restricted specifications that are significant at the 5% level in Table 3. Grey shading indicates confidence bands of 90%, 95% and 99%.

	(1)		(2)		(3)	(4)
	$\Delta \ln G_t$	$\Delta \ln Y_t$	$\Delta \ln G_t$	$\Delta \ln Y_t$	$\Delta \ln G_t$	$\Delta \ln G_t$
a) LAG STRUCTURE $q=2$						
<i>Cointegrating eq.</i>						
γ	0.939*** (32.462)		1		0.951*** (33.497)	1
g	0.242		0.185		0.225	0.185
<i>Error correction</i>						
α_G, α_Y	-0.052*** (-4.798)	-0.008 (-0.980)	-0.054*** (-4.414)	-0.001 (-0.086)	-0.054*** (-4.766)	-0.054*** (-4.419)
<i>Restrictions</i>						
Constraints	-		$\gamma = 1$		$\alpha_Y = 0$	$\gamma = 1,$ $\alpha_Y = 0$
Likelihood Value	1579.712		1577.821		1579.296	1577.818
LR Statistic	-		3.780		0.832	3.788
Deg. of Freed.	-		1		1	2
p -Value	-		0.052		0.362	0.150
b) LAG STRUCTURE $q=6$						
<i>Cointegrating eq.</i>						
γ	0.933*** (34.998)		1		0.951*** (34.784)	1
g	0.242		0.185		0.225	0.185
<i>Error correction</i>						
α_G, α_Y	-0.058*** (-4.080)	-0.017* (-1.911)	-0.057*** (-4.080)	-0.001 (-0.923)	-0.059*** (-4.411)	-0.056*** (-4.001)
<i>Restrictions</i>						
Constraints	-		$\gamma = 1$		$\alpha_Y = 0$	$\gamma = 1,$ $\alpha_Y = 0$
Likelihood Value	1573.361		1570.467		1571.630	1570.017
LR Statistic	-		5.789		3.463	6.689
Deg. of Freed.	-		1		1	2
p -Value	-		0.016		0.063	0.035

Table 3: Estimated Vector Error Correction Model for US data, 1947Q1 to 2013Q2 for lags $q=2$ and $q=6$.

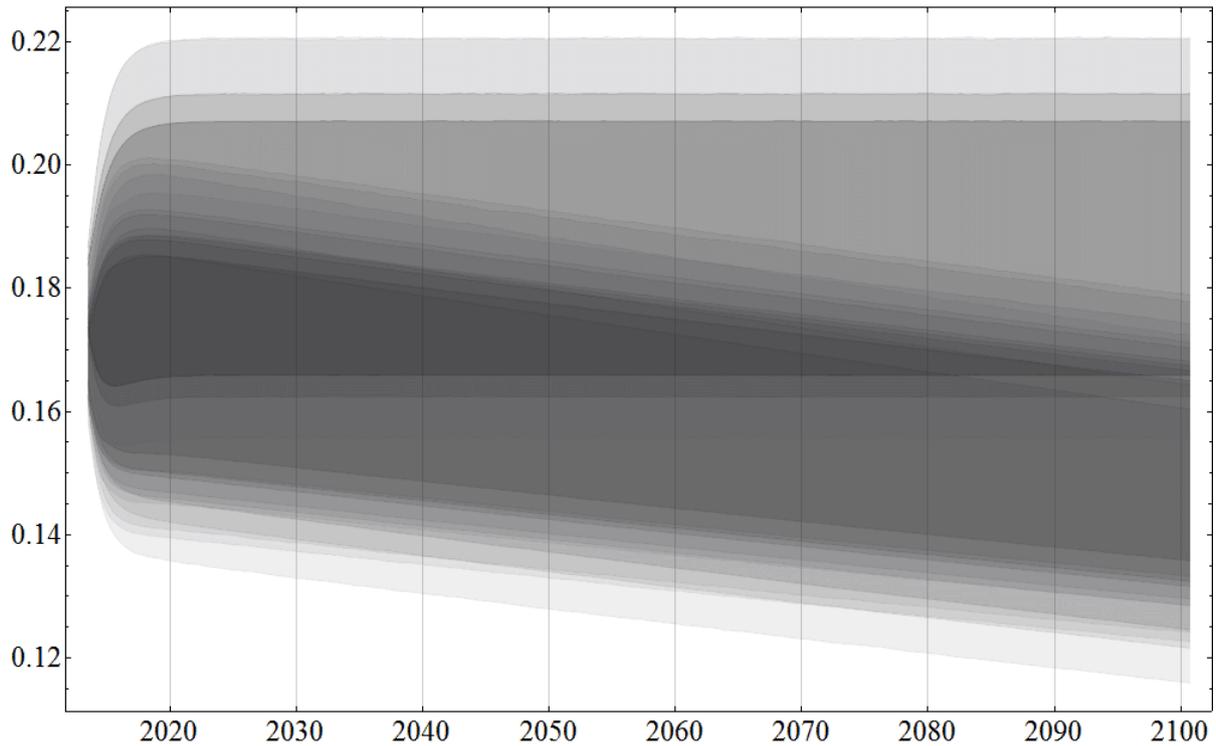


Figure 5: The overlapping confidence intervals for the forecasts in Figure 4.

time, decades or even centuries may pass before the value of $\gamma G_t/Y_t$ declines by any significant amount. Instead we can use the various versions of (33)—the unrestricted version, and those restricted ones we cannot reject at the 5% level—to generate the long-run forecasts of $\gamma G_t/Y_t$ in Figure 4.

Consider first the behavior of the forecasts for $\gamma G_t/Y_t$ when the estimated values of γ are unrestricted, and fall within the range of 0.933 to 0.951. The central forecasts do not vary much with the differences in the lag structure; only the size of the confidence intervals around them differ appreciably. The forecasts themselves express the behaviour of an economy with scale effects mentioned in Section 2, for the case where the value of γ falls strictly between zero and one and output is growing. As the size of the economy grows, either because of per-capita output growth or the increasing size of the work force, the share devoted to government consumption declines as its growth fails to completely keep pace with that of net output. In this scenario, the optimal tax rate also declines gently through the length of the forecast.

In the bottom two panels of Figure 4, where the value of γ is constrained to equal one, the forecast values of $\gamma G_t/Y_t$ are initially below g , which reflects the low ratio of G_t/Y_t at the end of the sample. However, subsequent forecasted values rise higher and slightly exceed the value of $g=0.185$.

Should a policy designed to minimise excess burden immediately set tax rates to equal these forecasts as implied by Conjecture 1, or at very least set a fixed rate of tax from mid-2013 to

the end of 2050 within the confidence intervals in Figure 4? If so, which set of forecasts should be chosen? Superimposing all six sets of confidence intervals yields Figure 5, where the darkest area, between 0.17 and 0.18, corresponds to the greatest (unweighted) overlap between all the different forecasts.

Having established in this section a strong empirical case for assuming that government consumption is a function of net output, and having already demonstrated in the previous section how such an assumption alters the nature of optimising fiscal policy, in the next section I consider the quantitative welfare implications of shifting the burden of tax between income generated from asset holdings and labour earnings, using these estimates. We can then also evaluate to what degree the small differences between the different estimated versions of (33) matter in terms of welfare.

4 Welfare Analysis

The purpose of this section is to numerically assess the theories and conjecture in Section 2, so as to quantify the magnitude of the welfare effects they imply for the US economy while incorporating the estimates from Section 3 regarding the relationship between government consumption and net output, and to juxtapose these results with those predicted by the canonical Chamley-Judd formulation, where government consumption is assumed to be growing at a fixed exogenous rate. To proceed, I assume a functional form for the utility function

$$u[c_t, l_t] = \ln c_t - \frac{l_t^{1+\frac{1}{v}}}{1+\frac{1}{v}} \quad (34)$$

where v corresponds to the Frisch elasticity of labour supply. I also assume that the aggregate production function takes the Cobb-Douglas form:

$$F[K_t, z_t L_t] = K_t^\alpha (z_t L_t)^{1-\alpha}. \quad (35)$$

To compare the welfare implications of shifts in fiscal policy, I calculate compensating differentials, measured in terms of a permanent increase in consumption. More formally, define $\{\check{\tau}_t^a\}_{t=1}^T$ as the sequence of tax rates on asset income associated with the new fiscal policy we wish to evaluate. The value of T may be finite or infinite, depending on whether the policy is assumed to be temporary or permanent. Such a policy generates flows of consumption and labour $\{c_t, l_t\}_{t=0}^\infty$, which can then be compared to $\{\check{c}_t, \check{l}_t\}_{t=0}^\infty$, the agents' counterfactual flows of consumption and labour given the initial tax policy. The compensating differential is

$$\pi \left(\check{\tau}_t^a \Big|_{t=0}^T \right) = e^{-\sum_{t=0}^\infty \beta^t N_t} e^{\sum_{t=0}^\infty \beta^t N_t} \left[\ln \frac{c_t}{\check{c}_t} + \frac{v}{1+v} \left(\check{l}_t^{1+\frac{1}{v}} - l_t^{1+\frac{1}{v}} \right) \right] - 1. \quad (36)$$

The welfare implications of different policies can now be evaluated by feeding their associated impulse responses into (36).

<i>Parameters and Initial Tax Rates</i>	
α	0.350
τ^c	0.050
τ^a	0.441
<i>Discount Rate and Depreciation (Quarterly)</i>	
β	0.9956
δ	0.0134
<i>Exogenous Growth Rates (Quarterly)</i>	
N_t/N_{t-1}	0.003
z_t/z_{t-1}	0.005
<i>Initial Asset Holdings (as Ratio of Annual Gross Output)</i>	
$B_0/F [K_0, z_0 L_0]$	0.895
$K_0/F [K_0, z_0 L_0]$	2.886

Table 4: The calibrated parameters of the model. The tax rate on asset income τ^a is the rate prior to policy changes.

4.1 Calibration

Microeconomic estimates of the Frisch elasticity labour supply vary from nearly zero to 0.5 for men and slightly higher for women. Surveying the recent literature, Reichling and Whalen (2012) conclude that a value of 0.4 provides the best central estimate, and this is the one employed by the Congressional Budget Office. By contrast, most dynamic stochastic general equilibrium models assume elasticities of one or two. Here I consider the two most extreme values analysed by Keane and Rogerson (2012): $v=0.1$ and $v=2$. As will be demonstrated below, the welfare effects generated by shifting the tax burden between capital and labour are remarkably robust to these two very different assumptions about the magnitude of this parameter, obviating the need to consider the implications of intermediate values.

Throughout, I constrain all shifts in fiscal policy to be fully financed—changes in the tax rate on asset income are fully compensated by offsetting changes to the tax rate on labour earnings, all the while the *ad valorem* tax rate on consumption remains constant.⁵ I assume there is an initial stock of public debt that must be serviced, but the stock of that debt always grows at the exogenous rates associated with the growth of the population and the steady state growth of per-capita income associated with technological improvement.

The share of government consumption and net output in Figure 2 is relatively stable, and I use the estimates in Table 3 of the cointegrating vector in (33) to quantify the relationship between them. Given the potential scale effects in this economy when $0 < \gamma < 1$, it seems most appropriate to use long-run averages for the underlying growth rates for population and labour augmenting technology across the same very long time horizon used to estimate (33) in Table 3. Hence for both N_t/N_{t-1} and z_t/z_{t-1} , the growth rates match the average quarterly growth rates from 1947Q1 to 2013Q2, where I assume that for an economy close to the balanced growth

⁵This is one of many possible ways to ensure that (9) and (10) are satisfied.

path the latter can be approximated by the per-capita growth rate of gross domestic product. Other relationships in the economy are not necessarily as stable or relevant, and even when they are, the appropriate data are not always available. Therefore both the tax rates and the share of capital in output are calculated using data from 1995 to 2011, following the procedure employed by Trabandt and Uhlig (2011) and using both the OECD and the European Union's AMECO databases. The initial stock of physical capital is chosen to match the average observed ratio of fixed assets to gross domestic product from 1995 to 2012.⁶ I choose the value of the subjective quarterly discount factor β that is consistent with the evolution of the Euler equation for consumption, given the long-run rates of growth and the capital output ratio. Finally, for the initial stock of public debt, instead of averaging over the preceding years, I choose a number that matches the ratio of the sum of publicly held US federal, state and local debt to gross output at the end of 2013Q2.⁷

4.2 Implications of the constrained estimates: $\gamma = 0$ versus $\gamma = 1$

Before considering the implications of the theoretical and empirical results from Sections 2 and 3, it is worthwhile to first examine how welfare would be affected by changes to US tax policy if, as was assumed by Chamley (1981), (1986), and Judd (1985), (1999), government consumption is exogenously determined.⁸ In our model, this is analogous to assuming that the value of γ in Sections 2 and 3 is equal to zero. Here, the immediate impact of any shift in the tax burden away from income derived from assets and towards labour earnings is to immediately raise the after tax rate of return on capital. This induces both an immediate drop in consumption and an increase in the amount of labour agents supply. The combined effect is to initiate a long period of capital accumulation during which de-trended per-capita consumption first recovers and ultimately exceeds its initial value, while the amount of labour gradually declines in response to both the higher rate at which it is being taxed, and an income effect associated with a diminution of the excess burden from capital income tax.

Inserting the impulse responses associated with different lower rates of taxation of asset income into (36), the welfare effects, expressed as compensating differentials in terms of permanent increases to consumption, increase as the burden of tax is shifted from assets and is maximised (or nearly so) for the two curves labeled $\gamma = 0, \nu = 0.1$ and $\gamma = 0, \nu = 2$ in Figure 6 and Table 5, in a manner consistent with the Chamley-Judd results, when the tax on asset

⁶The annual data necessary to calculate the rates of tax and share of capital are not yet available for the year 2012 as of this writing. Though the stock of consumer durables is often included in the capital stock and the flow of consumption services they generate are treated as part of output, here, to maintain consistency with the narrower definition of output in Section 3, we treat durable consumption as part of consumption. The main effect is to slightly lower the calibrated value of the rate of depreciation.

⁷Federal Debt Held by the Public [FYGFDPUN] and Liability of State and Local Governments, Excluding Employee Retirement Funds; Credit Market Instruments [SLGSDODNS]. *Data Source:* <http://research.stlouisfed.org/fred2/>.

⁸All simulations of tax changes and their welfare implications were calculated using a shooting algorithm. Programs available from the author by request.

income is completely eliminated ($\bar{\tau}^a = 0$).⁹ Reflecting the logic of Harberger triangles, nearly half the maximum welfare benefit is achieved when the tax rate τ^a is lowered from its initial value of 0.441 to 0.35. Beyond that point marginal improvements in welfare decrease rapidly reaching the equivalent of a 3.21% permanent increase in consumption if $\nu = 0.1$, and 3.07% if $\nu = 2$ (denoted by $\pi(0)$ in Table 5). The (rather small) difference between the two welfare measures reflects the degree to which the higher taxes on labour are themselves distortionary owing to the elasticity of the labour supply. Overall, the impact of eliminating the tax on asset income is the equivalent in consumption terms of about one and a half years of per-capita output growth.

Consider how this measure contrasts with the results when we use the values of the estimation from columns (2)a and (4)a in Table 3, where γ is constrained to equal one and the value of g is estimated to be 0.185. First, decreases in the tax rate on asset income generate patterns of welfare changes, using the two different values of ν , that are so close together they are represented by one curve in Figure 6. The elasticity of labour supply is nearly irrelevant here. Second, welfare is maximised not at the zero tax rate, where the value of $\pi(0)$ in Table 5 indicates a welfare increase equivalent to a 0.911% to 0.912% increment to permanent consumption. Instead the maximum welfare benefit is attained at the value of $\bar{\tau}^a = 0.185$ (see the rows that correspond to (2)a and (4)a in Table 5), validating the prediction made in Conjecture 1 that the optimal fixed rate of tax τ^a is equal to g . Indeed, although Theorem 1 and Corollary 2 refer to the long run, the results generated by an immediate and permanent change to the tax rate conform with their predictions, and those of Theorem 2 and Corollary 3 as well. Third, the maximum welfare gain, denoted by $\pi(\bar{\tau}^a)$ in Table 5, is equivalent to only a 1.243% to 1.245% permanent increase in consumption, less than half of what pertains when $\gamma = 0$ and the tax is eliminated. The implication is that, though from the perspective of a welfare maximising representative agent, the existing tax rate on asset income in the United States is presently set too high, the maximum benefit of reducing it is achieved when it is cut by slightly more than half, from 0.441 to 0.185, rather than by eliminating it completely. Furthermore, the maximal benefit to welfare that can be attained from any shift in the burden of taxation between asset income and labour earnings is much smaller than is commonly asserted in the literature, because there, government consumption is typically assumed not to respond to changes in the overall size of the economy.

⁹In fact the maximum is attained at small positive rates of taxation. The reason is that the tax on asset income is immediately reduced at the same time as it is announced. This has two contradictory effects on welfare: it reduces distortions because of the elasticity of capital supply in the long run, but, because capital supply is inelastic in the short run, it also bestows a costly lump-sum subsidy that the government must finance in the future. Only in the vicinity of the point where the tax is eliminated, and the welfare benefits of reducing the long-run distortions are nearly exhausted, does the this latter effect dominate. Even then it is too small to discern in Figure 6. Introducing a lag of two to three years between the time the policy is announced and its implementation, eliminates this slight non-monotonicity.

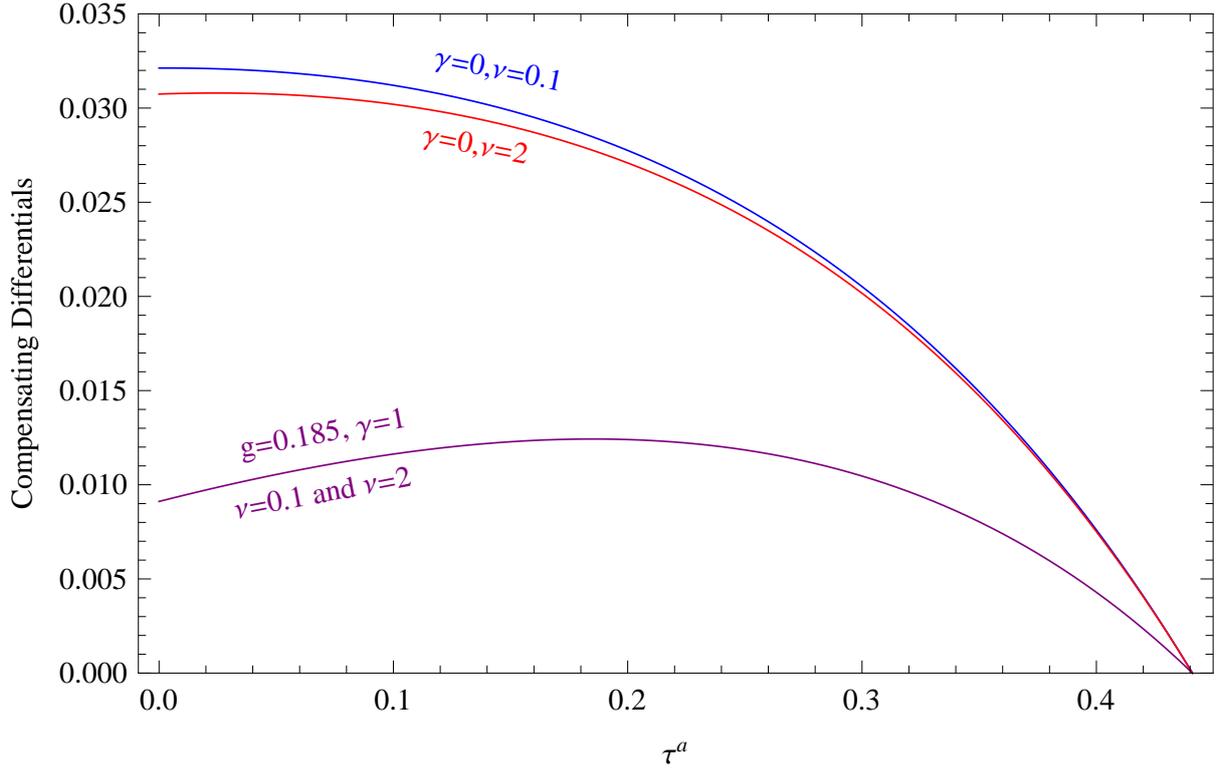


Figure 6: Welfare effects of lowering the tax rate on asset income from 0.441 in terms of permanent increases in consumption for $\gamma=0$ and $\gamma=1$.

4.3 Implications of the unconstrained estimates: $0 < \gamma < 1$, with constant rates of taxation

Suppose the value of γ is set between zero and one, in accordance with the unconstrained estimates in Table 3. Unlike the cases where $\gamma = 0$ or $\gamma = 1$, here the share of government expenditure in net output, and hence also the optimal tax rate, decline over time, as seen in the first two rows of Figure 4. This also means that when considering the welfare effects implied by a change in tax policy, not only are the new paths of consumption and labour $\{\check{c}_t, \check{l}_t\}_{t=0}^{\infty}$ dynamic, but the paths associated with the initial policy $\{\bar{c}_t, \bar{l}_t\}_{t=0}^{\infty}$ are dynamic as well. Rather than considering the evolution of the economy as it adjusts from one balanced growth path to another, the point of comparison here is an economy that is, before the change in policy is initiated, already a very great distance from convergence to a balanced growth path.

So if at the moment when the policy changes, the economy has not converged to a balanced growth path, what starting point best matches the analysis above? More specifically, given the parameters, growth rates and initial tax rates in Table 4, along with particular estimated values of γ and g , is it possible to set the initial capital output ratio, the debt burden and the share of government expenditure independently? The answer is no. Indeed, given the parameters in Table 4 and a particular set of estimates for γ and g , and the initial capital output ratio, we cannot choose a fixed ratio of public debt to annual output and an initial share

of government expenditure independently. Indeed, given these parameter values, choosing any reasonable capital to output ratio implies that government expenditure is slightly above 0.184, the historical average between 1947 and 2013. In what follows, I maintain consistency between the different versions of the model by keeping the same parameter values, hold fixed the ratio of public debt to annual output at 0.895, and choose an initial capital stock consistent with a ratio of capital to annual output of 2.886, all the while allowing the declining share of government expenditure to initially be somewhat higher than 0.184.

Finally, as explained in Sections 2 and 3, if the aggregate economy continues to grow because of population increase $N_t/N_{t-1} > 1$, technological improvement $z_t/z_{t-1} > 1$, or both, and the value of γ falls strictly between zero and one, output growth outpaces that of government consumption until the size of government expenditure as a share of net output reduces to zero in the limit. To avoid this unrealistic outcome, I assume that government consumption evolves according to the power function relationship $G[K_t, z_t L_t] = g(F[K_t, z_t L_t] - \delta K_t)^\gamma$ from the initial period $t = 0$, when the new policy is announced and implemented, to the end of period $T - 1$, when it reaches $g(F[K_{T-1}, z_{T-1} L_{T-1}] - \delta K_{T-1})^\gamma$. From period T onward, subsequent government consumption evolves by simply growing at the same exogenous rate as technology z_t and population N_t , in a manner analogous to the way I assume public debt is growing from the very beginning. I perform the simulations with two different values of T , 150 and 350. This means the period when government consumption is endogenous corresponds to either the remaining quarters from 2013Q3 till mid-century in 2050Q4, or to the end of the century, from 2013Q3 to 2100Q4.

I proceed by first considering policies identical to those analysed for the case of $\gamma = 1$, where the tax rate on asset income changes to a new fixed value and then never changes again, but using the values of g and γ that correspond to the unconstrained estimates from columns (1)a and (1)b in Table 3, and also column (3) where net output is weakly exogenous. Given that the unconstrained estimated values of γ from Table 3 are so close in value to one, it is not surprising that the general pattern of compensating differentials in Figure 7 appears so similar to the curve that corresponds to $\gamma = 1$ in Figure 6. Once again the complete abolition of the tax on asset income is welfare improving, because the initial tax rate of 0.441 is so very high. Overall the benefits are not particularly large, and again hardly influenced by the value we choose for the elasticity of labour supply. When I set $g = 0.242$, $\gamma = 0.933$, corresponding to the unrestricted estimation of (33) with lag length of $q = 2$, and set $v = 2$ and $T = 150$, the value of $\pi(0)$ in Table 5 is the equivalent of only a 0.771% permanent increase in consumption, and when $g = 0.242$, $\gamma = 0.939$, corresponding to the unrestricted estimation of (33) with a lag length of $q = 6$, and $v = 0.1$ and $T = 350$, the value of $\pi(0)$ rises to 0.986%. When the model is calibrated using the different estimates in Table 3, all the values of $\pi(0)$ in Table 5 fall between these two numbers.

If the social planner is constrained to immediately change the tax rate to one fixed value, the highest possible welfare improvement, the equivalent of a 1.304% increase in consumption is achieved when the model is calibrated with $g = 0.242$, $\gamma = 0.933$, $v = 0.1$ and $T = 350$ and

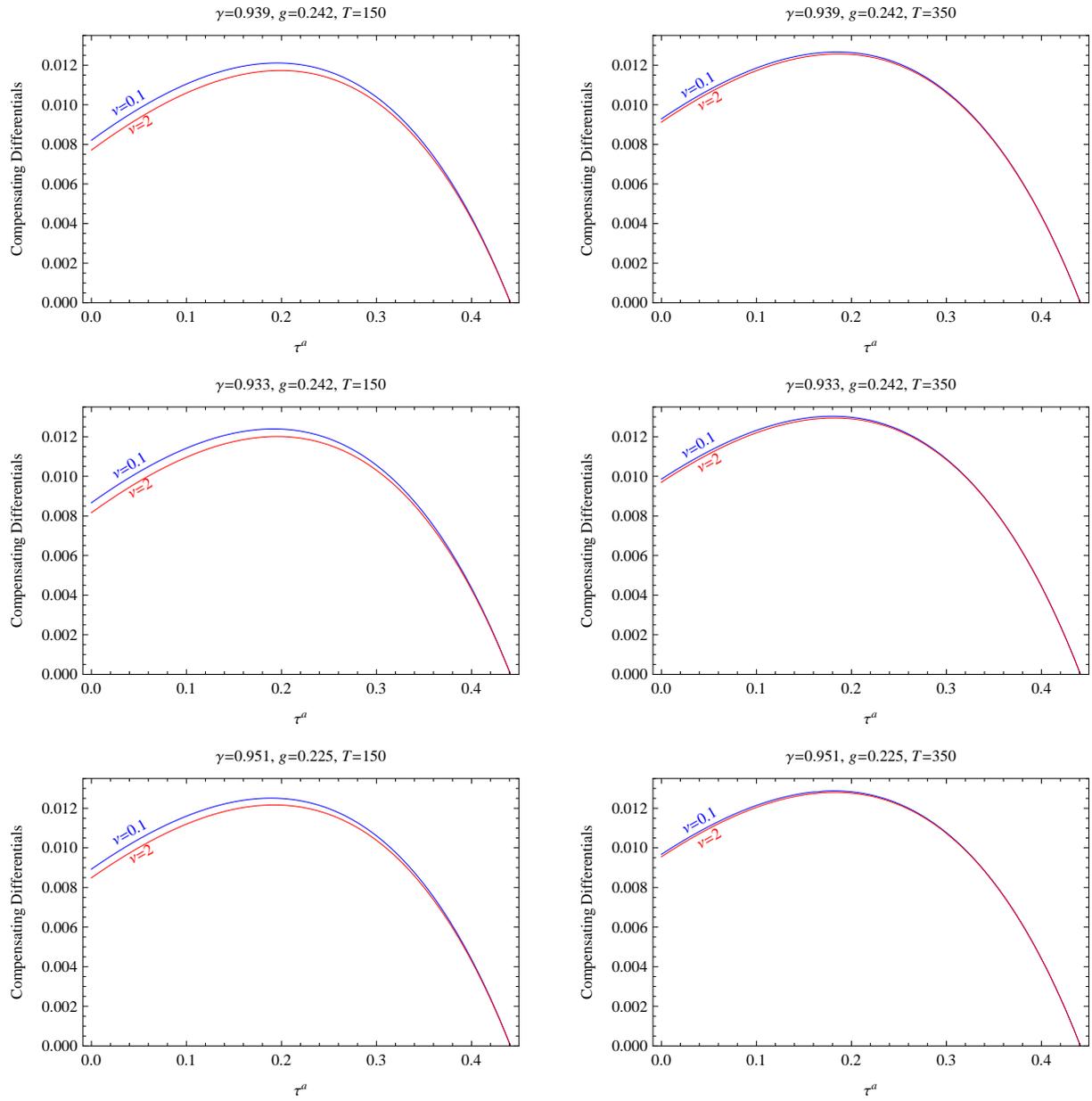


Figure 7: Welfare effects of lowering the tax rate on asset income from 0.441 in terms of permanent increases in consumption. The values of g and γ correspond to the estimates in column (1) and (3) in Table 3.

the tax rate on asset income is lowered from its initial value of 0.441 to $\bar{\tau}^a = 0.181$. When the model is calibrated with $g = 0.242$, $\gamma = 0.939$, $v = 2$ and $T = 150$, the highest achievable improvement in welfare is 1.173% where $\bar{\tau}^a = 0.2$. Overall, taking in both the restricted and unrestricted estimations, the results in Figures 6 and 7, as well as Table 3, suggest that the optimal fixed rate of taxation on asset income is somewhere between 0.18 and 0.2, a result that accords with the predictions of Theorem 2 and Corollary 3. A policy of lowering tax rates on asset income to within this range will produce the maximum welfare benefit equivalent to between a 1.173% and 1.304% increase in consumption, and no more.

4.4 Sequences with changing rates of tax

Suppose policy makers are no longer restricted to shifting between one fixed rate of tax on asset income and another as assumed in Theorem 2 and Corollary 3, but instead can choose tax rates that change over time, in accordance with Theorem 3, Corollary 4 and Conjecture 1. Let $\{\bar{\tau}_t^a\}_{t=1}^\infty$ denote the sequence of tax rates that obtain when the model is simulated with the tax rate on asset income set to equal $\gamma g (F[K_t, z_t L_t] - \delta K_t)^{\gamma-1}$, and let $\pi(\bar{\tau}_t^a)$ denote the welfare effects in terms of compensating differentials, generated by adoption of this policy. Conjecture 1 indicates that the improvements to welfare associated with setting the tax rate equal to $\gamma g (F[K_t, z_t L_t] - \delta K_t)^{\gamma-1}$ should dominate the policy associated with the fixed tax rates $\bar{\tau}^a$. If $\gamma = 0$ or $\gamma = 1$, this distinction is not meaningful, and the optimal policy is still to set the tax rate in each period to $\tau_t^a = 0$ or $\tau_t^a = g$ respectively, so the focus here is on those instances where $0 < \gamma < 1$. Again, given that net output is growing, the value of $\gamma g (F[K_t, z_t L_t] - \delta K_t)^{\gamma-1}$ declines and so any sequence of optimal tax rates is declining over time as well. As before, to prevent the share of government consumption from reducing to zero in the limit, I assume that from period $T = 150$ or $T = 350$ onwards, its share of net output stabilises.

In every case in Table 5, the values of $\pi(\bar{\tau}_t^a)$ are greater than $\pi(\bar{\tau}^a)$, confirming the predictions of Conjecture 1. At the same time, the differences are not large—allowing the tax rate to vary yields only small increments to welfare beyond those already achieved by lowering them to the relevant fixed value $\bar{\tau}^a$. If indeed the share of government expenditure continues to gently decline before stabilising at the end of the century, the best this policy can achieve is a welfare improvement of 1.310% in terms of permanent consumption for the case where $g = 0.242$, $\gamma = 0.933$, $v = 0.1$ and $T = 350$, compared to 1.304% if the tax rate on asset income is fixed at 0.181. Once more, though the prevailing burden on asset income is considerably higher than is optimal, the potential benefits of reducing it are still far more modest than is often assumed to be the case.

Finally, for completeness' sake, consider the welfare implications of introducing, not the sequence of tax rates on asset income denoted by $\{\bar{\tau}_t^a\}_{t=1}^\infty$ that match the values of $\gamma g (F[K_t, z_t L_t] - \delta K_t)^{\gamma-1}$, as calculated within the model simulation, but rather the sequence of forecasts generated by the estimation of the model (33) in Figure 4. The forecasts in the two lower panels of Figure 4, where the value of γ is constrained to equal one, generate sequences of $\gamma g (F[K_t, z_t L_t] - \delta K_t)^{\gamma-1}$ that are nearly constant. Hence it is not surprising that the corresponding values of the compen-

	γ	g	T	$100 \times \pi(0)$	$\bar{\tau}^a$	$100 \times \pi(\bar{\tau}^a)$	$100 \times \pi(\tilde{\tau}_t^a)$	$100 \times \pi(\tilde{\tau}_t^a)$
	0	-	-	3.213	0	3.213	-	-
$v=0.1$	(1)b	0.933	0.242	150	0.866	0.192	1.239	1.248
				350	0.986	0.181	1.304	1.310
	(1)a	0.939	0.242	150	0.821	0.196	1.211	1.220
				350	0.929	0.185	1.267	1.273
	(3)a	0.951	0.225	150	0.892	0.189	1.251	1.258
				350	0.967	0.181	1.288	1.293
(3)b			150	0.967	0.181	1.288	1.293	
			350	0.967	0.181	1.288	1.293	
(2)a	1	0.185	-	0.911	0.185	1.243	-	1.243
(4)a	1	0.185	-	0.911	0.185	1.243	-	1.243
	0	-	-	3.074	0	3.074	-	-
$v=2.0$	(1)b	0.933	0.242	150	0.816	0.194	1.201	1.203
				350	0.970	0.183	1.295	1.299
	(1)a	0.939	0.242	150	0.771	0.200	1.173	1.175
				350	0.912	0.184	1.257	1.260
	(3)a	0.951	0.225	150	0.849	0.192	1.217	1.218
				350	0.955	0.182	1.281	1.283
(3)b			150	0.955	0.182	1.281	1.283	
			350	0.955	0.182	1.281	1.283	
(2)a	1	0.185	-	0.912	0.185	1.245	-	1.245
(4)a	1	0.185	-	0.912	0.185	1.245	-	1.245

Table 5: The optimising policies and corresponding welfare measures for different values of γ and g .

sating differentials $\pi(\tilde{\tau}_t^a)$ in Table 5 are nearly identical to $\pi(\bar{\tau}^a)$. Beyond that the values of $\pi(\tilde{\tau}_t^a)$ are uniformly lower than either $\pi(\tilde{\tau}_t^a)$ or $\pi(\bar{\tau}^a)$ for each parameterisation of the model, but the differences are not substantial. Either way, it seems that a policy of fixing the tax rate on asset income to the appropriate level $\bar{\tau}^a$ in Table 5 is one that both is easy to implement and secures much of any potential welfare benefit that can be attained by changing fiscal policy.

5 Conclusion

Peacock and Wiseman's study *The Growth of Public Expenditure in the United Kingdom*, first published in 1961, was partly motivated by the desire to test a proposition first stated by Adolph Wagner in 1883:

The “law of increasing expansion of public, and particularly state, activities” becomes for the fiscal economy the law of increasing expansion of fiscal requirements. Both the State’s requirements grow and, often more so, those of local authorities.....That law is the result of empirical observation in progressive countries, at least in our Western European civilization; its explanation, justification and cause is the pressure for social progress and the resulting changes in the relative spheres of private and public economy, especially compulsory public economy. Financial stringency may hamper the expansion of state activities, causing their extent to be conditioned by revenue rather than the other way round, as is more usual. But in the long run the desire for development of a progressive people will always overcome these financial difficulties.¹⁰

Their work appeared to confirm Wagner’s prediction that government expenditure would not only grow with the size of the economy, it would take an increasing share of output—they found that government consumption of goods and services rose from 6.6% to 22.7% of gross national product in the years between 1890 and 1955 (spending on transfers and subsidies rose from 2.3% to 13.9%). By contrast, I find that government consumption expenditure in the US between 1947 and 2013 is indeed closely related to net domestic product, but the proportion is either stable or declining very slowly, and hence more consistent with the type of relationship described by an American contemporary of Wagner, Henry Carter Adams, writing in 1898:

On the contrary, it seems reasonable to assume that with each increment in the social product the people will conceive it to be to their advantage to invest added sums in the machinery of government. From the point of view of investment, therefore, as well as from a consideration of the satisfaction to be secured from the activities of the State, may we conclude that the fiscal demands of government will increase along with, if not in proportion to, the general social income.¹¹

Given the high rates of taxation on asset income that currently prevail in the United States, any reduction, including all the way to zero, will yield some welfare benefit. Nonetheless, once the link between government consumption and net output is recognised, the optimality of setting the tax rate to zero and shifting all the burden to labour earnings disappears. Instead a more modest shift, one that would see the rate of tax on asset income drop by slightly more than half, will yield the highest welfare improvement. Moreover, the potential welfare gain is less than half what we would expect if we ignore the linkage between government consumption and output. This result is highly robust to both the different estimates of the cointegrating relationship between government consumption and net output, as well as the widest plausible range of possible values for the elasticity of labour supply.

¹⁰Adolph Wagner, *Finanzwissenschaft*, Third edition, Leipzig 1883. Translated to English by Nancy Cooke in Richard A. Musgrave and Alan T. Peacock, ed. *Classics in the Theory of Public Finance*, New York: St Martin’s Press, 1967, pg. 8.

¹¹Henry Carter Adams, *The Science of Finance: An Investigation of Public Expenditures and Public Revenues*, New York: Henry Holt and Company, 1898, pg. 39.

The policy implication of this paper, that an efficient fiscal policy is one that sets the tax on asset income to a positive rate only slightly below the rate of tax on labour earnings, is in qualitative terms, nearly identical to that in Reis (2011). In her paper the taxing authority cannot distinguish between entrepreneurial labour income and returns to capital. Similarly, Correia (1996) demonstrates that if some productive factors cannot be taxed, some of the burden of financing government expenditure should fall on capital income. Banks and Diamond (2010) cite these considerations as underpinning their rejection of zero taxation of asset income in their recommendations published in the *Mirlees Review* which studied possible reforms to the United Kingdom's tax system. A parallel strand of the literature first developed by Aiyagari (1995) argues in favour of taxing the income derived from capital, as a means of suppressing its over-accumulation, because uninsurable idiosyncratic risk leads to precautionary saving. However, there is no reason to assume *a priori* that a model that incorporates both mechanisms, the endogeneity of government consumption and the difficulty of distinguishing between productive inputs or imposing a tax on some of them, will generate still higher optimal taxes on asset income that compound these two effects.

The optimality of positive tax rates on asset income also emerges in most of the models derived in a Mirleesian, rather than a Ramsey framework. However, the underlying mechanism in Mirleesian models that justifies these taxes, the asymmetry in the availability of information available to agents and the tax authority, as in Golosov *et al.* (2003), is unlikely to interact with the reasoning based on the endogeneity of government consumption here, in any manner that would indicate that the two mechanisms reinforce each other to justify rates of tax higher than those implied by each argument in isolation.

6 Appendix

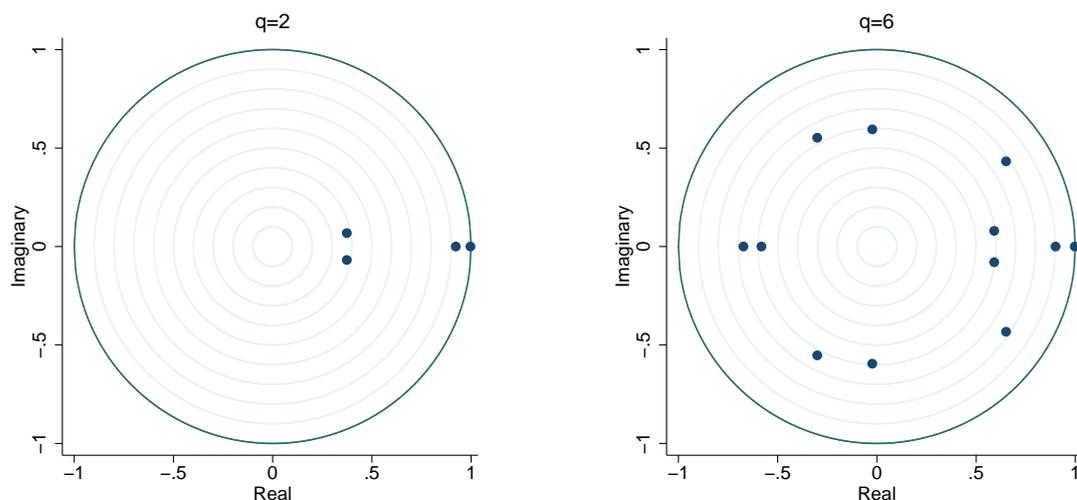


Figure 8: Eigenvalues of the estimated VAR system with lag lengths q set to 2 and 6.

	(1)		(2)		(3)	(4)
	$\Delta \ln G_t$	$\Delta \ln Y_t$	$\Delta \ln G_t$	$\Delta \ln Y_t$	$\Delta \ln G_t$	$\Delta \ln G_t$
<i>Cointegrating eq.</i>						
γ	0.939*** (32.462)		1		0.951*** (33.497)	1
g	0.242		0.185		0.225	0.185
<i>Error correction</i>						
α_G, α_Y	-0.052*** (-4.798)	-0.008 (-0.980)	-0.054*** (-4.414)	-0.001 (-0.086)	-0.054*** (-4.766)	-0.054*** (-4.419)
$\Delta \ln G_{t-1}$	0.257*** (4.484)	-0.083** (-2.000)	0.267*** (4.634)	-0.081* (-1.950)	0.259*** (4.513)	0.267*** (4.634)
$\Delta \ln G_{t-2}$	0.177*** (3.100)	0.037 (0.890)	0.189*** (3.285)	0.036 (0.863)	0.180*** (3.147)	0.189*** (3.285)
$\Delta \ln Y_{t-1}$	0.065 (0.749)	0.338*** (5.377)	0.083 (0.952)	0.348*** (5.548)	0.066 (0.765)	0.083 (0.952)
$\Delta \ln Y_{t-2}$	0.030 (0.340)	0.101 (1.596)	0.037 (0.425)	0.111* (1.760)	0.029 (0.329)	0.037 (0.425)
η_G, η_Y	0.004*** (3.244)	0.005*** (5.200)	0.004*** (2.951)	0.005*** (5.056)	0.004*** (3.218)	0.004*** (2.951)
R^2	0.244	0.167	0.234	0.163	0.244	0.234
\bar{R}^2	0.229	0.150	0.219	0.147	0.229	0.219
F -statistic	16.555	10.268	15.697	10.041	16.527	15.697

Table 6: Estimated Vector Error Correction Model for US data, 1947Q1 to 2013Q2 for lags $q=2$.

	(1)		(2)		(3)	(4)
	$\Delta \ln G_t$	$\Delta \ln Y_t$	$\Delta \ln G_t$	$\Delta \ln Y_t$	$\Delta \ln G_t$	$\Delta \ln G_t$
<i>Cointegrating eq.</i>						
γ	0.933*** (34.998)		1		0.951*** (34.784)	1
g	0.242		0.185		0.225	0.185
<i>Error correction</i>						
α_G, α_Y	-0.058*** (-4.080)	-0.017* (-1.911)	-0.057*** (-4.080)	-0.0096 (-0.923)	-0.059*** (-4.411)	-0.056*** (-4.001)
$\Delta \ln G_{t-1}$	0.212*** (3.424)	-0.036 (-0.810)	0.225*** (3.615)	-0.031 (-0.700)	0.214*** (3.470)	0.225*** (3.615)
$\Delta \ln G_{t-2}$	0.137** (2.196)	0.050 (1.121)	0.150** (2.378)	0.054 (1.206)	0.140** (2.240)	0.150** (2.378)
$\Delta \ln G_{t-3}$	0.078 (1.231)	-0.044 (-0.982)	0.087 (1.359)	-0.043 (-0.941)	0.080 (1.270)	0.087 (1.359)
$\Delta \ln G_{t-4}$	0.036 (0.570)	-0.080* (-1.790)	0.044 (0.700)	-0.079* (-1.768)	0.039 (0.616)	0.044 (0.700)
$\Delta \ln G_{t-5}$	-0.103* (-1.681)	0.108** (2.470)	-0.097 (-1.557)	0.105** (2.390)	-0.100 (-1.624)	-0.097 (-1.556)
$\Delta \ln G_{t-6}$	0.093 (1.551)	0.068 (1.591)	0.102* (1.678)	0.066 (1.528)	0.097 (1.617)	0.102* (1.678)
$\Delta \ln Y_{t-1}$	0.012 (0.131)	0.313*** (4.826)	0.034 (0.367)	0.328*** (5.062)	0.013 (0.144)	0.034 (0.367)
$\Delta \ln Y_{t-2}$	-0.019 (-0.199)	0.161** (2.416)	-0.006 (-0.065)	0.171** (2.549)	-0.018 (-0.195)	-0.006 (-0.065)
$\Delta \ln Y_{t-3}$	0.156* (1.658)	-0.115* (-1.782)	0.162* (1.704)	-0.110 (-1.637)	0.155 (1.645)	0.162* (1.704)
$\Delta \ln Y_{t-4}$	0.011 (0.121)	-0.070 (-1.039)	0.018 (0.190)	-0.063 (-0.934)	0.011 (0.116)	0.018 (0.190)
$\Delta \ln Y_{t-5}$	-0.031 (-0.332)	-0.081 (-1.222)	-0.023 (-0.247)	-0.075 (-1.125)	-0.031 (-0.331)	-0.023 (-0.247)
$\Delta \ln Y_{t-6}$	0.008 (0.089)	0.014 (0.215)	0.019 (0.211)	0.023 (0.358)	0.008 (0.089)	0.019 (0.211)
η_G, η_Y	0.003** (2.169)	0.005*** (4.756)	0.002 (1.586)	0.005*** (4.453)	0.003** (2.089)	0.002 (1.586)
R^2	0.270	0.238	0.259	0.229	0.271	0.259
\bar{R}^2	0.231	0.197	0.220	0.188	0.232	0.220
F -statistic	6.976	5.872	6.595	5.594	6.996	6.595

Table 7: Estimated Vector Error Correction Model for US data, 1947Q1 to 2013Q2 for lags $q=6$.

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